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* Program Number: 68K Monitor for S100Computers.com / N8VEM S-100 board
* Written by      : John Monahan
* Date Created   : 11/11/2011
* Description    : Basic monitor for 68K S-100 board
*
* 'A=Memmap      C=XMODEM(Bin) D=Disp RAM   E=Echo          F=Fill RAM'
* 'G=Goto RAM    H=Math          I=Time      K=Menu          L=Test Ints'
* 'M=Move RAM    N=IDE Menu      Q=Port I/O  U=Serial Test  S=Subs RAM'
* 'T=Type RAM    V=Verify RAM    X=Signals  Y=Patch        Z=Back to Z80'
*
*-----*
;          V1.5      03/07/2012 ;Corrected line length display of RAM (D & T Commands)
;          V1.6      03/07/2012 ;Added initialization of Interrupt routines in low RAM
;          V1.7      03/08/2012 ;Add test interrupts routine, "L" CMD.
;          V1.8      03/09/2012 ;Code to switch back to Z80, and hardware signals analysis
;          V1.9      03/18/2012 ;Added IDE Board Diagnostic Section
;          V1.91     03/27/2012 ;Substitute RAM redone
;          V2.0      04/02/2012 ;Added IDE Menu Items and Y command
;          V2.1      04/26/2013 ;Fixed numerous small bugs, RAM display map,D,F,M X commands
etc
;          V2.2      04/27/2013 ;Display RAM (D CMD) also displays ASCII
;          V2.3      04/23/2014 ;Allow output to 16 bit ports (>0FFH), DMA1* port switch is now
00EEH
;          V2.4      04/30/2014 ;Cleanup console I/O routines, add serial port I/O
;          V2.5      05/2/2014  ;Added XMODEM .bin file download capabilities over serial port
;          V2.6      06/12/2014 ;Corrected QO/QI port bug

;  >>>>>> Please note the IDE Board Diagnostic section is not complete yet. Do NOT use <<<<<<<<

;Programming a Wellon VP-290 with 28C256 EEPROMS.
;Assemble and make a S68 file (Project Menu for EASy68K)
;Load first, even byte in dropdown menu for "File Mode"
;For "From File Address(Hex) enter FD0000 (Note "To Buffer Address (HEX) is 0)
;File Size is 8000 (for X28C256's)
;For "Auto Format Detect" use Motorola S
;Repeat, for second EEPROM using Odd Bytes for "File Mode"
;
;

BELL      EQU      $07
BLANK     EQU      $20
CR        EQU      $0D
LF        EQU      $0A
ESC       EQU      $1B
TAB       EQU      $09
SOH      EQU      1   ; For Modem etc.
EOT      EQU      4
ACK      EQU      6
NAK      EQU      $15

;Note, only one of the following 3 equates can be 1
SIMULATOR EQU      0   ;Set to 1 if using EASy68K Simulator (Console I/O will be via
software interrupts)
S100_TEST EQU      0   ;Set to 1 if using S100 RAM (We will not use INT's for console I/O)
ROM_CODE  EQU      1   ;Set to 1 for ROM code (We will not use INT's for console I/O)

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;Propeller Console IO S-100 board or SD SYSTEMS VIDIO BOARD FOR CONSOLE I/O(<---These must
configured for your hardware)

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KEYSTAT      EQU      $00FF0000
KEYIN        EQU      $00FF0001 ;Console input port. Normally the Propeller Driven S-100
Console-IO Board
KEYOUT       EQU      $00FF0001 ;Console output port. Normally the Propeller Driven S-100
Console-IO Board

;----- THIS IS MY PORT TO OUTPUT DATA TO HP 4050T LASAR PRINTER (IMSAI 8PIO Board)

PRINTER_STATUS EQU      $00FF0005 ;IN, HP PARRELL PORT
PRINTER_OUT    EQU      $00FF0005 ;OUT
PRINTER_STROBE EQU      $00FF0004 ;OUT
DIAG_LEDS     EQU      $00FF0005 ;OUT (Will use this port initially for diagnostic LED
display)

;----- S100Computers Serial I/O BOARD PORT ASSIGNMENTS (A0-AC)

BCTL         EQU      $00FF00A0 ;CHANNEL B CONTROL PORT ASSIGNMENTS OF THE ZILOG SCC CHIP
ACTL         EQU      $00FF00A1 ;CHANNEL A CONTROL (Base Port)
BDTA         EQU      $00FF00A2 ;CHANNEL B DATA
ADTA         EQU      $00FF00A3 ;CHANNEL A DATA
MODEM_ERR_LIMIT EQU      8 ;Max number of Modem serial port re-reads aborting (See XMODEM_BIN)
SERIAL_RETRY EQU      8000 ;Default number of times to try reading serial port before
aborting. Not critical.
SPEAKER_DELAY EQU      1000 ;Slight delay for speak synthesizer
;
PortA_8255   EQU      $00FF00A8 ;A port of 8255 ;<--- Adjust as necessary
PortB_8255   EQU      $00FF00A9 ;B port of 8255
PortC_8255   EQU      $00FF00AA ;C Port of 8255
PortCtrl_8255 EQU      $00FF00AB ;8255 configuration port

AinBout8255cfg EQU      %10011000 ;Set 8255 ports:- A input, B output,
;C(bits 0-3) output, (bits 4-7)input

USB_DATA     EQU      $00FF00AC ;PORT ASSIGNEMENT FOR DLP-USB Controller chip
USB_STATUS   EQU      $00FF00AA ;Status port for USB port (Port C of 8255, bits 6,7)

USB_RXE      EQU      $80 ;If Bit 7 = 0, data available to recieve by S-100 Computer
USB_TXE      EQU      $40 ;If Bit 6 = 0 data CAN be written for transmission to PC

IOBYTE       EQU      $00FF00EF ;IOBYTE Port on S100Computers SMB Board.

; BIT MAP OF PORT 0EFH:- X X X X X X X X (11111111=NORMAL CONFIG)
; | | | | | | | | ..For Z80 Monitor, 0=CONSOLE DATA TO PRINTER ALSO
; | | | | | | | | ....For 8086 Monitor, 0=Force MSDOS Consol output to
CGA/VGA Board instead of Propeller board
; | | | | | | | | .....For 8086 Monitor, 0=Do not initilize extra ROMS
; | | | | | | | | .....For 8086 Monitor, 0=Debug data for all MSDOS 10H &
15H INT's to Serial Port and external display
; | | | | | | | | .....Unused
; | | | | | | | | |-----For Monitor, 0=Consol Output,(not input), via
ACIA Serial port on S100Computers Serial-IO Board
; | | | | | | | | .....For CPM3, 0=Force reformat of Memory disk
upon any CPM3 cold re-boot
; | | | | | | | | |
; | | | | | | | | .....For CPM3, 0=Write protect Memory disk for
CPM3
; | | | | | | | | | For 8086 Monitor 0=Prevent doing a JMPF to 500H
after 8086 reset (to CPM86 boot)
; | | | | | | | | | Normally a test is made to see if the CPM86 Boot is
already in RAM at 500H

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;                                     If it is, a 8086 reset will bypass the monitor and go
directly there.
;                                     (see Init: in 8086 Monitor)
;
;                                     Note if IOBYTE = 00xxxxxx,           This will force the 8086 hardware
diagnostic test after reset.                                     (See code at FFFF0H in this
;                                                                     8086 monitor)
;
;----- S100Computers MSDOS BOARD PORT ASSIGNMENTS

NS_EOI          equ      $20 ;Non specific end of interrupt command
MASTER_PIC_PORT equ      $00FF0020 ;Hardware port the 8259A is assigned (two ports 20H & 21H)

MasterICW1      equ      %00010111 ;EDGE triggered, 4 bytes, single Master, ICW4 needed
MasterICW2      equ      $8 ;Base address for 8259A Int Table (IBM-PC uses 8X4 = 20H)
MasterICW3      equ      $0 ;No slave
MasterICW4      equ      %00000011 ;No special mode, non buffer, Auto EOI, 8086. ;<<<<,

CMOS_PORT       EQU      $00FF0070 ;Base Port for CMOS Chip
CMOS_VALID      EQU      $00FF000D ;To check DS12887 CMOS chip is present and OK (Note AT-BIOS
uses 0EH)
CMOS_REGA       EQU      $00FF000A ;CMOS REGISTER A

TIMER           EQU      $00FF0040 ;Base port of 8254
TIM_CTL         EQU      $00FF0043
COUNTS_SEC     EQU      $18
COUNTS_MIN     EQU      1092
COUNTS_HOUR    EQU      $07 ;Seems this value is used with AT/CMOS chip (was 65543 on PC)

UPDATE_TIMER    EQU      $80

CMOS_SECONDS    EQU      $0 ;RAM offsets for CMOS Registers
CMOS_MINUTES    EQU      $2
CMOS_HOURS      EQU      $4

;----- S100Computers IDE BOARD PORT ASSIGNMENTS (30-34H)

;Ports for 8255 chip. Change these to specify where the 8255 is addressed,
;and which of the 8255's ports are connected to which IDE signals.
;The first three control which 8255 ports have the IDE control signals,
;upper and lower data bytes. The forth one is for mode setting for the
;8255 to configure its ports, which must correspond to the way that
;the first three lines define which ports are connected.

IDEportA        EQU      $00FF0030 ;lower 8 bits of IDE interface
IDEportB        EQU      $00FF0031 ;upper 8 bits of IDE interface
IDEportC        EQU      $00FF0032 ;control lines for IDE interface
IDECtrlPort     EQU      $00FF0033 ;8255 configuration port
IDEDrivePort    EQU      $00FF0034 ;To select the 1st or 2nd CF card/drive

IFEQ SIMULATOR ;If SIMULATOR = 0 (Normal EEPROM)
Patch_RAM       EQU      $00F40000 ;Location of Patch code area
ENDC

IFNE SIMULATOR ;If SIMULATOR = 1 (For testing here within EASy68K & S100 RAM)
Patch_RAM       EQU      $00008000
ENDC

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IDE_Reset_Delay EQU      $20 ;Time delay for reset/initilization (~66 uS, with 8MHz 8086, 1 I/O
wait state)

READcfg8255      EQU      %10010010   ;Set 8255 IDEportC out, IDEportA/B input
WRITEcfg8255     EQU      %10000000   ;Set all three 8255 ports output

;IDE control lines for use with IDEportC.

IDEa0line        EQU      $01 ;direct from 8255 to IDE interface
IDEa1line        EQU      $02 ;direct from 8255 to IDE interface
IDEa2line        EQU      $04 ;direct from 8255 to IDE interface
IDEcs0line       EQU      $08 ;inverter between 8255 and IDE interface
IDEcs1line       EQU      $10 ;inverter between 8255 and IDE interface
IDEwrline        EQU      $20 ;inverter between 8255 and IDE interface
IDERdline        EQU      $40 ;inverter between 8255 and IDE interface
IDERstline       EQU      $80 ;inverter between 8255 and IDE interface
;
;Symbolic constants for the IDE Drive registers, this makes the
;code more readable than always specifying the address pins

REGdata          EQU      IDEcs0line
REGerr           EQU      IDEcs0line + IDEa0line
REGsecCnt        EQU      IDEcs0line + IDEa1line
REGsector        EQU      IDEcs0line + IDEa1line + IDEa0line
REGcylinderLSB   EQU      IDEcs0line + IDEa2line
REGcylinderMSB   EQU      IDEcs0line + IDEa2line + IDEa0line
REGshd           EQU      IDEcs0line + IDEa2line + IDEa1line ; (0EH)
REGcommand       EQU      IDEcs0line + IDEa2line + IDEa1line + IDEa0line ; (0FH)
REGstatus        EQU      IDEcs0line + IDEa2line + IDEa1line + IDEa0line
REGcontrol       EQU      IDEcs1line + IDEa2line + IDEa1line
REGastatus       EQU      IDEcs1line + IDEa2line + IDEa1line + IDEa0line

;IDE Command Constants. These should never change.

COMMANDrecal     EQU      $10
COMMANDread      EQU      $20
COMMANDwrite     EQU      $30
COMMANDinit      EQU      $91
COMMANDid        EQU      $EC
COMMANDspindown  EQU      $E0
COMMANDspinup    EQU      $E1
;
; IDE Status Register:
; bit 7: Busy 1=busy, 0=not busy
; bit 6: Ready 1=ready for command, 0=not ready yet
; bit 5: DF 1=fault occured on the IDE drive
; bit 4: DSC 1=seek complete
; bit 3: DRQ 1=data request ready, 0=not ready to xfer yet
; bit 2: CORR 1=correctable error occured
; bit 1: IDX vendor specific
; bit 0: ERR 1=error occured

MAXSEC          EQU      $3D ;Sectors per track for CF my Memory drive, Kingston CF 8G. (CPM
format, 0-3CH)
;translates to LBA format of 1 to 3D sectors, for a total of 61
sectors/track.
;This CF card actully has 3F sectors/track. Will use 3D for my CPM86 system
because
;my Seagate drive has 3D sectors/track. Don't want different CPM86.SYS
files around
;so this program will also work with a Seagate 6531 IDE drive

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DOS_MAXSEC      EQU      $3F      ;For MS-DOS BIOS Setting "Hard Disk" to Custom type (CF Card,
63 Sectors/track)
DOS_MAXHEADS    EQU      $10      ;16 head(s)
DOS_MAXCYL_L    EQU      $FF      ;Low Byte maximum cylinder (sent via INT 13H's in CH)
DOS_MAXCYL      EQU      1024     ;Max cylinders
DOS_MAXSEC_CYL EQU      $FF      ;3FH, maximum sector number (bits 5-0)+ two Cyl High Bits
(Sectors numbered 1....x)

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;-----Other Hardware Equates -----

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HOLD_STATE      EQU      $80      ;Set Keyboard flag to indicate a Pause is required
NO_HOLD_STATE   EQU      $7F      ;To clear the above flag

SW68K           EQU      $00FF00EE ;OUTPUT TO THIS PORT 02H, SWITCHES THE 68000 CPU BACK to
the Z80 in hardware
                ;In my system using the V2 SMB.

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;----- START -----

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IFNE ROM_CODE      ;If ROM_CODE = 1 (Use with ROM)
    ORG $00FD0000

    DC.L  $00FD8100 ;SSP = FD8100H
    DC.L  $00FD0020 ;PC = FD1020H

    ORG $00FD0020 ;Will start monitor here in ROM
ENDC

IFNE SIMULATOR    ;If SIMULATOR = 1 (Use for testing in EASy68K simulator)
    ORG $00000000
    BRA SKIP      ;jump up to 1000H because Int vectors will overwrite code here

    ORG $1000     ;In both EASy68K and S100 test modes will place code at 1000H
SKIP:
    ENDC

    IFNE S100_TEST ;If SIMULATOR= 1 (Use for testing, for S100 RAM use the ROM stack)
        ORG $00000000
        BRA SKIP      ;jump up to 1000H because Int vectors will overwrite code here

        ORG $1000     ;In both EASy68K and S100 test modes will place code at 1000H
SKIP:
    ENDC

    MOVE.L #KEYSTAT,A0 ;Point to status Port 0H (CRT, Propeller Console IO Board)
    MOVE.L #KEYIN,A1   ;Point to hardware Port 01H (CRT, Propeller Console IO Board)
START:
    LEA Signon,A2      ;Show we are alive
    BSR PRINT_STRING

    BSR SERIAL_INITILIZE_A ;Initilize Consoel-IO board Serial Port A
    BSR SERIAL_INITILIZE_B ;Initilize Consoel-IO board Serial Port B
    LEA SMSG,A2
    BSR SPEAK_STRING    ;Speak out signon the message

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BSR LOW_RAM_INITILIZE ;Initilize low RAM Int Vectors (for all modes)

;Initilize HIGH RAM to 0 (Used by IDE Routines)
LEA BeginRAM,A2 ;START OF WORK RAM (PAST STACK)
MOVE.L #(EndRAM-BeginRAM),D0 ;BYTES TO ZERO
CLR.L D1

ZERO_RAM: MOVE.B D1,(A2)+ ;ZERO MEMORY
SUBQ.L #1,D0
BNE ZERO_RAM

loop: LEA Prompt,A2 ;Show CR,LF,'>'
BSR PRINT_STRING
CLR.L D1 ;Just to be on the safe side
BSR GETCHAR ;Get a menu character (WITH ECHO)
AND.B #$7F,D1 ;Just to be safe, strip any potential parity bit
BSR TOUPPER ;Lower case to Upper case for lookup table

CMP.B #'A',D1
BLT ERR
CMP.B #'Z',D1
BGT ERR
SUB.B #'A',D1
LSL.L #2,D1 ;X4 for offset into table
LEA ctable,A2 ;Start of cmd table
MOVE.L (A2,D1),A3 ;Add X4 offset
JMP (A3)

;-----
ERR: CMP.B #CR,D1 ;If CR just return
BEQ loop
MOVE.L D1,-(A7) ;> Save D1
LEA BadCmdMsg,A2 ;Non menu selection
BSR PRINT_STRING
MOVE.L (A7)+,D7 ;Put D1 in D7
BSR PUTLONG_D7
LEA H_MSG_CRLF,A2 ;H, then CR,LF
BSR PRINT_STRING
BRA loop ;Back to start for next command

;-----
SHOW_MENU: ;Display this monitors commands on CRT
LEA Menu,A2 ;Menu string
BSR PRINT_STRING
BRA loop ;Back to start for next command

;-----
MEM_MAP: MOVE.L #0,A3 ;A Command. Do Memory Map. Pointer to RAM area A3=0
NEWLINE: BSR CRLF
MOVE.L A3,D7
BSR PUTLONG_D7 ;Print long value of D7
MOVE.L #64,D3 ;64 characters across per line
MOVE.L #$FFFFFFFF,D5

MOVE.B #BLANK,D1
BSR PUTCHAR

START1: MOVE.L (A3),D1 ;Is there RAM/ROM there

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NOT.L   D1
MOVE.L  D1, (A3) ;See if we can flip bits
MOVE.L  (A3), D6
CMP.L   D1, D6
BNE NOT_RAM
NOT.L   D1 ;Put back original data
MOVE.L  D1, (A3)
MOVE.B  #'R', D1
BRA DONE_TEST

NOT_RAM: MOVE.L  (A3), D1 ;Is there RAM/ROM there
CMP.L   D5, D1 ;Chances are it is empty if FFFFF's!
BEQ EMPTY
MOVE.B  #'p', D1
BRA DONE_TEST

EMPTY:  MOVE.B  #'.' , D1
DONE_TEST: BSR PUTCHAR

ADD.L   #$2000, A3 ;No matter what point to next 2K byte section

SUBQ.L  #1, D3
TST.L   D3 ;Have we done 32X2 characters across
BEQ NEWLINE

MOVE.L  A3, D4
CMP.L   #$0FE0000, D4 ;Have we done all the RAM area
BLE START1
BRA LOOP ;Back to start of menu

;-----
;-----

DISPLAY_RAM: ;D Command. Display Bytes in RAM
BSR GETLONG_D7 ;Get start address
CMP.B   #' ', D2 ;Is it valid
BNE ERROR
MOVE.L  D7, A3 ;Save in A3

BSR GETLONG_D7 ;End address
CMP.B   #CR, D2 ;Is it valid
BNE ERROR
MOVE.L  D7, A4 ;Save in A4

CMP.L   A3, A4
BEQ LOOP ;If the same nothing to display
BGE PARMS_OK
MOVE.L  A3, A5 ;Else swap values
MOVE.L  A4, A3
MOVE   A5, A4

PARMS_OK: ADD.L   #1, A4 ;End + 1
PARMS_OK5: MOVE.L  A3, -(A7) ;Save A3
MOVE.L  A4, -(A7) ;Save A4

PARMS_OK2: BSR CRLF ;New line
MOVE.L  A3, D7
BSR PUTLONG_D7 ;Show current address
BSR SPACE
MOVE.B  #16, D4 ;Count of characters across

PARMS_OK1: MOVE.B  (A3), D6 ;Get RAM byte to D6
BSR PUTBYTE_D6 ;Show Byte value

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BSR SPACE

ADDQ.L #1,A3 ;Shift pointer up one
SUBQ.B #1,D4 ;Have we done 16 characters across
TST.B D4
BNE PARMS_OK1 ;Not 16 across, then next byte

MOVE.L (A7)+,A4 ;Next Show ASCII for this line, Back to original RAM location
MOVE.L (A7)+,A3 ;Were stored above
BSR SPACE
BSR SPACE
MOVE.B #16,D4 ;Count of characters across

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PARMS_OK4: MOVE.B (A3),D1 ;Get RAM byte to D1
CMP.B #' ',D1
BLT PRINT_DOT
CMP.B #$7F,D1
BGE PRINT_DOT

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PARMS_OK6 BSR PUTCHAR ;Print character

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ADDQ.L #1,A3
SUBQ.B #1,D4
TST.B D4 ;Have we done 16 characters across
BNE PARMS_OK4

CMP.L A3,A4 ;Are we done wit total data display yet
BLE LOOP
BRA PARMS_OK5

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PRINT_DOT:

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MOVE.B #'.',D1
BRA PARMS_OK6

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FILL_RAM: ;F Command. Fill RAM with one byte value

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BSR GETLONG_D7 ;Get start address
CMP.B #',',D2 ;Is it valid
BNE ERROR
MOVE.L D7,A3 ;Save in A3

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```

BSR GETLONG_D7 ;End address
CMP.B #',',D2 ;Is it valid
BNE ERROR
MOVE.L D7,A4 ;Save in A4

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```

CMP.L A3,A4
BEQ LOOP ;If the same nothing to display
BGE FILL_OK
MOVE.L A3,A5 ;Else swap values
MOVE.L A4,A3
MOVE A5,A4

```

```

FILL_OK: ADD.L #1,A4 ;End + 1
BSR GETBYTE_D7 ;get Hex value in D7 (0-FF)
CMP.B #CR,D2 ;Is it valid
BNE ERROR

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FILL_OK1: MOVE.B D7,(A3) ;D7 to RAM
ADDQ.L #1,A3
CMP.L A3,A4 ;Are we done yet

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```
BLE LOOP
BRA FILL_OK1
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```
SUBS_RAM:          ;S Command. Substitute RAM with one byte values
BSR GETLONG_D7    ;Get start address
CMP.B   #CR,D2    ;Is it valid
BNE ERROR
MOVE.L   D7,A3    ;--- Save in A3 (also leave in A7)
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```
SUBS_RAM2: BSR CRLF      ;New line
MOVE.L   A3,D7
BSR PUTLONG_D7    ;Show current address
MOVE.B   #BLANK,D1
BSR PUTCHAR

MOVE.B   #8,D4    ;Count of characters across
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```
SUBS_RAM3: MOVE.B   (A3),D6
BSR PUTBYTE_D6    ;Display current byte

BSR GETBYTE_D7    ;Get new Hex value in D7 (0-FF)
CMP.B   #ESC,D2   ;If ESC then we are done
BEQ LOOP
CMP.B   #CR,D2    ;Also CR we are done
BEQ LOOP
TST.B   D3        ;Is byte count = 0 from GETBYTE_D7 above then no update
BEQ SUBS_RAM1     ;Is already on screen

MOVE.B   D7,(A3)  ;Substitute in the byte
BRA SUBS_RAM4
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SUBS_RAM1: MOVE.B   #' ',D1
BSR PUTCHAR
BSR PUTCHAR
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```
SUBS_RAM4: BSR PUTCHAR

ADDQ.L   #1,A3    ;Next byte
SUBQ.B   #1,D4
BNE SUBS_RAM3
BRA SUBS_RAM2
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```
MOVE_RAM:          ;M Command. Move RAM
BSR GETLONG_D7    ;Get start address
CMP.B   #',',D2   ;Is it valid
BNE ERROR
MOVE.L   D7,A3    ;Save in A3

BSR GETLONG_D7    ;End address
CMP.B   #',',D2   ;Is it valid
BNE ERROR
MOVE.L   D7,A4    ;Save in A4

CMP.L   A3,A4
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    BEQ LOOP      ;If the same nothing to display
    BGE MOVE_OK
    MOVE.L  A3,A5  ;Else swap values
    MOVE.L  A4,A3
    MOVE    A5,A4

MOVE_OK:        ADD.L  #1,A4  ;End + 1
                BSR GETLONG_D7 ;End address
                CMP.B  #CR,D2 ;Is it valid
                BNE ERROR
                MOVE.L D7,A5  ;Save in A5

MOVE_OK1:      MOVE.B  (A3)+,(A5)+
                CMP.L  A3,A4
                BGE MOVE_OK1
                BRA LOOP

;-----
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QUERY_PORT:    CLR.L  D1  ;Just to be on the safe side
                BSR GETCHAR ;get a menu character
                BSR TOUPPER ;Lower case to Upper case

                CMP.B  #'I',D1 ;Is it a port input request
                BEQ QUERY_IN
                CMP.B  #'O',D1 ;Is it a port output request
                BEQ QUERY_OUT
                BRA ERROR  ;Must be an error

QUERY_IN:      BSR GETLONG_D7 ;Get (Byte only) Port Hex value in D7 (0-FF)
                TST.B  D3  ;Byte count > 0
                BEQ LOOP
                CMP.B  #ESC,D2 ;If ESC then we abort
                BEQ LOOP
                CMP.B  #CR,D2 ;If CR then we also abort
                BNE ERROR
                MOVE.B  D7,D6 ;store in D6 (also in D7)

                LEA PortMsg,A2 ;'Port xx'
                BSR PRINT_STRING
                BSR PUTBYTE_D6 ;Display Port value
                MOVE.B  #'H',D1 ;'H'
                BSR PUTCHAR
                MOVE.B  #'=',D1 ;'='
                BSR PUTCHAR

                MOVE.L  #$00FF0000,D6 ;Point to Port RAM area
                OR.B  D7,D6 ;OR in the hardware value
                MOVE.L  D6,A2 ;A2 now has port address
                MOVE.B  (A2),D6 ;Get value at port

                BSR PUTBYTE_D6 ;Display Byte value
                MOVE.B  #'H',D1 ;'H'
                BSR PUTCHAR
                MOVE.B  #' ',D1 ;' '
                BSR PUTCHAR
                MOVE.B  #'(',D1 ;' ('
                BSR PUTCHAR
                BSR PUTBITS_D6
                MOVE.B  #')',D1 ;')'
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```
BSR PUTCHAR
BRA LOOP
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QUERY_OUT: BSR GETLONG_D7 ;Get Port value (value in D7, 0-FFFF)
TST.B D3 ;Byte count > 0
BEQ LOOP
CMP.B #ESC,D2 ;If ESC then we abort
BEQ LOOP
CMP.B #',',D2 ;If CR then we also abort
BNE ERROR
MOVE.L D7,D4 ;<<< Store (WORD) port # in D4

BSR GETBYTE_D7 ;Get data in D7 (0-FF)
TST.B D3 ;Byte count > 0
BEQ LOOP
CMP.B #ESC,D2 ;If ESC then we are done
BEQ LOOP
CMP.B #CR,D2 ;If CR then we are done
BNE LOOP
MOVE.L D7,D5 ;<<< Store data (BYTE) to send to port in D5

LEA PortMsg2,A2 ;'Send to Port xxxx'
BSR PRINT_STRING
MOVE.L D4,D6
BSR PUTWORD_D6 ;Display Port value (as a word)
MOVE.B #'H',D1 ;'H'
BSR PUTCHAR
MOVE.B #'-',D1 ;'-'
BSR PUTCHAR
MOVE.B #'>',D1 ;'>'
BSR PUTCHAR

MOVE.B D5,D6
BSR PUTBYTE_D6 ;Display Byte value
MOVE.B #'H',D1 ;'H'
BSR PUTCHAR

MOVE.L #$00FF0000,D6 ;Point to Port RAM area
OR.B D4,D6 ;OR in the hardware value
MOVE.L D6,A2 ;A2 now has port address
MOVE.B D5,(A2) ;Send actual data to port
BRA LOOP
```

```
-----
-----
```

```
ASCII_RAM: ;T Command. Display ASCII in RAM

BSR GETLONG_D7 ;Get start address
CMP.B #',',D2 ;Is it valid
BNE ERROR
MOVE.L D7,A3 ;Save in A3

BSR GETLONG_D7 ;End address
CMP.B #CR,D2 ;Is it valid
BNE ERROR
MOVE.L D7,A4 ;Save in A4

CMP.L A3,A4
BEQ LOOP ;If the same nothing to display
```

```

BGE ASCII_OK
MOVE.L  A3,A5    ;Else swap values
MOVE.L  A4,A3
MOVE    A5,A4

```

```

ASCII_OK:  BSR CRLF      ;New line
           MOVE.L  A3,D7
           BSR PUTLONG_D7 ;Show current address
           MOVE.B  #BLANK,D1
           BSR PUTCHAR
           MOVE.B  #32,D4  ;Count of characters across

```

```

ASCII_OK1: MOVE.B  (A3),D1 ;Get RAM byte to D6
           CMP.B   #' ',D1
           BLT UNPRINTABLE
           CMP.B   #0x7F,D1
           BGE UNPRINTABLE

```

```

ASCII_OK2: BSR PUTCHAR

           SUBQ.B  #1,D4   ;Have we done 64 characters across
           TST.B   D4
           BEQ ASCII_OK

           ADDQ.L  #1,A3
           CMP.L   A3,A4   ;Are we done yet
           BLE LOOP
           BRA ASCII_OK1

```

```

UNPRINTABLE:
           MOVE.B  #'.',D1
           BRA ASCII_OK2

```

```

;-----
-----

```

```

VERIFY_RAM:      ;M Command. Verify two RAM locations have the same data
                BSR GETLONG_D7 ;Get start address
                CMP.B  #' ',D2 ;Is it valid
                BNE ERROR
                MOVE.L  D7,A3   ;--- Save in A3

                BSR GETLONG_D7 ;End address
                CMP.B  #' ',D2 ;Is it valid
                BNE ERROR
                MOVE.L  D7,A4   ;--- Save in A4

                CMP.L  A3,A4
                BEQ LOOP      ;If the same nothing to display
                BGE VERIFY_OK
                MOVE.L  A3,A5   ;Else swap values
                MOVE.L  A4,A3
                MOVE    A5,A4

```

```

VERIFY_OK:  ADD.L  #1,A4   ;End + 1
           BSR GETLONG_D7 ;End address
           CMP.B  #CR,D2  ;Is it valid
           BNE ERROR
           MOVE.L  D7,A5   ;--- Save in A5

```

```

VERIFY_OK1: CMP.B  (A3)+, (A5)+
           BNE BAD_MATCH
VERIFY_OK2: CMP.L  A3,A4   ;Are we done yet
           BGE VERIFY_OK1

```

```
BRA LOOP
```

```
BAD_MATCH: BSR CRLF      ;New line
            MOVE.L  A3,D7
            SUBQ.L  #1,D7  ;Backup to problem
            MOVE.L  D7,A3
            BSR PUTLONG_D7 ;Show first address
            MOVE.B  #BLANK,D1
            BSR PUTCHAR
            MOVE.B  (A3)+,D6
            BSR PUTBYTE_D6
            MOVE.B  #BLANK,D1

            BSR PUTCHAR
            BSR PUTCHAR

            MOVE.L  A5,D7
            SUBQ.L  #1,D7  ;Backup to problem
            MOVE.L  D7,A5
            BSR PUTLONG_D7 ;Show first address
            MOVE.B  #BLANK,D1
            BSR PUTCHAR
            MOVE.B  (A5)+,D6
            BSR PUTBYTE_D6
            BSR CRLF
            BRA VERIFY_OK2
```

```
-----
-----
```

```
ECHO_ASCII:          ;E Command. Get ASCII typed on keyboard and display on Console
            LEA ECHO_MSG,A2 ;"Will echo each keyboard char on screen"
            BSR PRINT_STRING
```

```
ECHO2:              BSR CRLF      ;New line
                    CLR.L  D1    ;Just to be on the safe side
                    BSR GETCHAR ;get a character

                    CMP.B  #ESC,D1 ;If ESC then we abort
                    BEQ LOOP
                    CMP.B  #CR,D1  ;If CR then we also abort
                    BEQ LOOP
```

```
ECHO1:              CMP.B  #' ',D1
                    BLT NOASCII
                    CMP.B  #$7F,D1
                    BGE NOASCII
                    BSR PUTCHAR ;Echo character
                    BRA ECHO2
```

```
NOASCII:            MOVE.B  #' ',D1
                    BRA ECHO1
```

```
-----
-----
```

```
GOTO_RAM:           ;G Command . Go to a location in RAM and start from there.
                    BSR GETLONG_D7 ;Go to address in D7
                    CMP.B  #CR,D2  ;Is it valid
                    BNE ERROR
```

```

MOVE.L D7,A3 ;Save in A3
JMP (A3) ;That's all there is to it!

```

```

;-----
-----

```

```

HEX_MATH: ;H Command. Add/subtract two hex numbers.
BSR GETLONG_D7 ;Get First number
CMP.B #' ',D2 ;Is it valid
BNE ERROR
MOVE.L D7,D4 ;Save in D4

BSR GETLONG_D7 ;Get second number
CMP.B #CR,D2 ;Is it valid
BNE ERROR
MOVE.L D7,D5 ;Save in D5
MOVE D7,D6

LEA HEX_Data,A2 ;Hex data = string
BSR PRINT_STRING
ADD.L D7,D6 ;Total in D6
MOVE.L D6,D7
BSR PUTLONG_D7

LEA HEX_Data2,A2 ;Difference =
BSR PRINT_STRING
SUB.L D4,D5
MOVE.L D5,D7
BSR PUTLONG_D7
LEA H_MSG_CRLF,A2 ;'H'
BSR PRINT_STRING
BRA LOOP

```

```

;-----
-----

```

```

TEST_INTS: ;L Command setup interrupt vectors in RAM 0 -- 400H
BSR LOW_RAM_INITILIZE ;Make it a callable routine for later use.
LEA INTS_DONE_MSG,A2 ;'Interrupt vectors in RAM (0-400H) initilized'
BSR PRINT_STRING
MOVE.W #$2000,SR ;Allow ALL INTERRUPTS, SUPERVISOR MODE

```

```

INT_LOOP: MOVE.B #' ',D1 ;Continously print .....
BSR PUTCHAR ;Echo character
BSR GETSTAT ;Is there a keyboard character ready
BEQ INT_LOOP
BSR GETCHAR ;Get a keyboard character
CMP.B #ESC,D1 ;ESC to abort test
BEQ INT_LOOP1
BSR TOUPPER ;Lower case to Upper case
BSR PUTCHAR
BRA INT_LOOP

INT_LOOP1: MOVE.W #$2700,SR ;MASK OFF INTERRUPTS
BSR CRLF
BRA START ;Reload Monitor

```

```

LOW_RAM_INITILIZE:
MOVE.L #$8,A2 ;Skip (Reset vectors) STACK & ADDRESS vectors etc.

```

```

LEA BUS_ERROR,A3      ;8H = BUS ERROR
MOVE.L A3,(A2)+
LEA ADDRESS_ERROR,A3  ;CH = ADDRESS
MOVE.L A3,(A2)+
LEA ILLEGAL_ERROR,A3
MOVE.L A3,(A2)+
LEA ZERO_ERROR,A3
MOVE.L A3,(A2)+
LEA ILLEGAL_ERROR,A3
MOVE.L A3,(A2)+
LEA ILLEGAL_ERROR,A3
MOVE.L A3,(A2)+
LEA PRIVILEGE_ERROR,A3
MOVE.L A3,(A2)+
LEA TRACE_ERROR,A3
MOVE.L A3,(A2)+

MOVE.L #$28,A2 ;General Error, Starting at 1010 Illegal Opcode
LEA ABORTE,A3  ;Use default Error message
INIT0: MOVE.L A3,(A2)+
CMPA.L #$60,A2      ;Continue up to Spurious Interrupt (60H)
BMI.S INIT0

LEA SPURIOUS_INT,A3 ;Spurious Interrupt vector
MOVE.L A3,(A2)+
LEA L1_INTERRUPT,A3 ;Hardware Interrupts
MOVE.L A3,(A2)+
LEA L2_INTERRUPT,A3
MOVE.L A3,(A2)+
LEA L3_INTERRUPT,A3
MOVE.L A3,(A2)+
LEA L4_INTERRUPT,A3
MOVE.L A3,(A2)+
LEA L5_INTERRUPT,A3
MOVE.L A3,(A2)+
LEA L6_INTERRUPT,A3
MOVE.L A3,(A2)+
LEA L7_INTERRUPT,A3
MOVE.L A3,(A2)+

IFEQ SIMMULATOR      ;If SIMMULATOR = 0, i.e. we are in S100 or ROM mode, write this, else
skip
LEA TRAPS,A3         ;16 Trap vectors
INIT1: MOVE.L A3,(A2)+
CMPA.L #$C0,A2      ;Up to C0H
BMI.S INIT1

ENDC

MOVE.L #$C0,A2 ;Just to be sure we are at the correct place
LEA ABORTE,A3  ;Use default Error message

INIT2: MOVE.L A3,(A2)+ ;INITIALIZE VECTORS
CMPA.L #$400,A2   ;Up to end of all vectors (3FFH)
BMI.S INIT2
RTS ;All Done

;Below are the error messages
BUS_ERROR: MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
LEA BUS_ERROR_MSG,A2
BSR PRINT_STRING
MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
RTE

```

```

ADDRESS_ERROR:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA ADDRESS_ERROR_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE

ILLEGAL_ERROR:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA ILLEGAL_ERROR_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE

ZERO_ERROR:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA ZERO_ERROR_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE

PRIVILEGE_ERROR:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA PRIVILEGE_ERROR_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE

TRACE_ERROR:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA TRACE_ERROR_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE

SPURIOUS_INT:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA SPURIOUS_INT_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE

L1_INTERRUPT:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA L1_INTERRUPT_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE
    RTE

L2_INTERRUPT:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA L2_INTERRUPT_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
    RTE

L3_INTERRUPT:
    MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
    LEA L3_INTERRUPT_MSG,A2
    BSR PRINT_STRING
    MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS

```



RTE

## L4\_INTERRUPT:

```

MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
LEA L4_INTERRUPT_MSG,A2
BSR PRINT_STRING
MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
RTE

```

## L5\_INTERRUPT:

```

MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
LEA L5_INTERRUPT_MSG,A2
BSR PRINT_STRING
MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
RTE

```

## L6\_INTERRUPT:

```

MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
LEA L6_INTERRUPT_MSG,A2
BSR PRINT_STRING
MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
RTE

```

## L7\_INTERRUPT:

```

MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
LEA L7_INTERRUPT_MSG,A2
BSR PRINT_STRING
MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
RTE

```

## ABORTE:

```

MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
LEA INT_ERR_MSG,A2
BSR PRINT_STRING
MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
RTE

```

## TRAPS:

```

MOVEM.L D0-D7/A0-A6,-(A7) ;SAVE ALL REGISTERS
LEA TRAPS_ERR_MSG,A2
BSR PRINT_STRING
MOVEM.L (A7)+,D0-D7/A0-A6 ;POP ALL REGISTERS
RTE

```

```

;-----
----

```

## JMP\_Z80:

```

;Switch back to Z80 Master CPU
MOVE.L #SW68K ,D5 ;Point to status Port 0ECh for DMA1 switch line
MOVE.L D5,A2

MOVE.B #00,(A2) ;Currently will use TMA line #1 to switch in/out the 68K board
NOP ;<-- 68K Is held in HALT mode here until released again by the Z80/master

CPU

NOP
NOP
NOP
BRA LOOP

```

```

;-----
----

```

## SIGNALS:

```

;Setup hardware signal tests to look at S-100 signals pDBIN, pWR*

```



```

MOVE.W D2, (A3)
MOVE.W D2, (A3)
MOVE.W D2, (A3)
BRA WR_TEST1 ;Must Hit Reset button to abort

```

```

PATCH: ;Y Command, Quick patch to move RAM 4000H-9000H to F4000H & JUMP to it
LEA PATCH_MSG,A2 ;"Moving Code 4000H-9000H to F4000H, Then jump to that
location"
BSR PRINT_STRING ;The CPM3/Z80 SID program will place any test .bin file from a
disk to 4000H
;in RAM (no matter what its final ORG is).
MOVE.L #$4000,A3 ;This command will then move test versions of this monitor (or
any other
MOVE.L #$F4000,A5 ;program) up out of the way to F4000H and execute it from
there.
MOVE.L #$8000,D1 ;This should be large enough for a monitor copy

PATCH1: MOVE.B (A3)+, (A5)+
SUBQ.L #1,D1
BNE PATCH1
JMP Patch_RAM ;Jump to this loction

```

```

;*****
;*****
;
; Module to Test and diagnose the www.S100Computers.com IDE Board
; Normally the DMA buffers will reside in the RAM on the 68K board itself at 00FD9000H
;
;*****
;*****

```

```

MY_IDE: LEA DISPLAY_FLAG,A2 ;Do we have detail sector data display flag on or off
MOVE.B $FF,(A2) ;Set default to detailed sector display

```

```
BSR CLEAR_ID_BUFFER ;Clear ID Buffer
```

```
BSR SET_DRIVE_A ;Select the first Drive/CF card
```

```
;
BSR IDEinit ;Initialize the board and drive 0. If there is no drive abort
BEQ INIT1_OK
```

```
LEA INIT_1_ERROR,A2
```

```
BSR PRINT_STRING
```

```
BRA LOOP
```

```
INIT1_OK:
```

```
BSR SET_DRIVE_B ;Select the second Drive/CF card (Do not mess with CPM Drive 0)
```

```
;
BSR IDEinit ;Initialize drive 1. If there is no drive abort
```

```
BEQ INIT2_OK
```

```
BSR CLEAR_ID_BUFFER ;Clear ID Buffer
```

```
LEA INIT_2_ERROR,A2 ;Warn second IDE drive did not initialize
```

```
BSR PRINT_STRING
```

```
INIT2_OK:
```

```
BSR SET_DRIVE_A ;Back to first drive/CF Card
```

```

;      BSR DRIVE_ID      ;Get the drive 0 id info. If there is no drive just abort
;      BEQ INIT3_OK

      LEA BAD_DRIVE,A2
      BSR PRINT_STRING
;
INIT3_OK:      ;Set default position will be first sector block
      LEA IDE_Buffer+12,A2
      CMP.W #0,(A2) ;Is it non zero
      BNE INIT4_OK      ;If there are zero sectors then something wrong

      LEA BAD_DRIVE,A2      ;"Error obtaining first Drive ID"
      BSR PRINT_STRING
;
      BRA LOOP

INIT4_OK:      CLR.B (RAM_SEC) ;Sec 0
      MOVE.B #0,(RAM_TRK) ;Track 0

      LEA IDE_BUFFER,A4
      MOVE.L A4,(RAM_DMA)

;      BSR IDEinit ;For some reason this need to be here after getting the drive ID.
;                   ;otherwise sector #'s are off by one! (Probably because on non-LBA reads)
;      BSR WR_LBA ;Update LBA on "1st" drive

;----- MAIN IDE DRIVE DIAGNOSTIC MENU -----
IDE_LOOP:      LEA IDE_SIGNON0,A2 ;List IDE command options
      BSR PRINT_STRING

      CMP.B #0,(CURRENT_IDE_DRIVE)
      BNE SIGN_B
      LEA CURRENT_MSG_A,A2
      BRA IDE_LOOP0
SIGN_B:      LEA CURRENT_MSG_B,A2
IDE_LOOP0:      BSR PRINT_STRING

      CMP.B #0,(DISPLAY_FLAG) ;Do we have detail sector data display flag ON or OFF
      BNE IDE_LOOP1
      LEA IDE_SIGNON1,A2 ;"ON"
      BRA IDE_LOOP2
IDE_LOOP1:      LEA IDE_SIGNON2,A2 ;"OFF"
IDE_LOOP2:      BSR PRINT_STRING

      LEA IDE_SIGNON3,A2 ;List IDE command options
      BSR PRINT_STRING

      BSR DISPLAY_POSITION ;Display current Track,sector,head#

      BSR CRLF
      LEA IDE_MENU_CMD,A2 ;Enter a command
      BSR PRINT_STRING

      BSR GETCHAR ;Get a command from Console

```

```

        CMP.B  #ESC,D1 ;Abort if ESC
        BNE NOT_ESC
        BRA START    ;Back to start of Monitor

NOT_ESC:   BSR TOUPPER ;Lower case to Upper case

        IFNE SIMMULATOR      ;If SIMMULATOR = 1
        BSR PUTCHAR ;Echo character
        ENDC

        CMP.B  #'A',D1
        BLT ERR
        CMP.B  #'Z',D1
        BGT ERR
        SUBI.B #'A',D1
        LSL.L  #2,D1    ;X4 for offset into table
        LEA IDE_TABLE,A2    ;Start of cnd table
        MOVE.L (A2,D1),A3    ;Add in X4 offset
        JMP (A3)

;          INDIVIDUAL IDE DRIVE MENU COMMANDS

;-----Select Drive/CF card -----
SET_DRIVE_A:      ;Select First Drive
        LEA IDE_SEL_A,A2    ;Say so
        BSR PRINT_STRING
        CLR.B  D1

SELECT_DRIVE:
        MOVE.B  D1,CURRENT_IDE_DRIVE
        MOVE.B  D1,(IDEDrivePort)    ;Select Drive 0 or 1
        BSR CRLF
        BRA IDE_LOOP    ;Back to IDE Menu

SET_DRIVE_B:      ;Select Drive 1
        LEA IDE_SEL_B,A2    ;Say so
        BSR PRINT_STRING
        MOVE.B  #1,D1
        JMP SELECT_DRIVE

;----- Do the IDentify drive command, and display the IDE_Buffer -----
DRIVE_ID:
        BSR IDEwaitnotbusy
        BGE L_5
        CLR D1
        SUBQ.B #1,D1    ;NZ if error
        RTS    ;If Busy return NZ

L_5:
        MOVE.B  #COMMANDid,D4
        MOVE.B  #REGcommand,D5
        BSR IDEwr8D ;Issue the command

        BSR IDEwaitdrq ;Wait for Busy=0, DRQ=1
        BGE L_6
        BRA SHOWerrors

L_6:
        CLR.B  D6 ;256 words

        LEA IDE_Buffer,A4    ;Store data here
        BSR MoreRD16    ;Get 256 words of data from REGdata port to IDE_Buffer

        LEA msgmdl,A2    ;Print the drive's model number
        BSR PRINT_STRING

```

```

LEA IDE_Buffer+52,A2
MOVE.B #10,D3 ;Character count in words
BSR Print_ID_Info ;Print [A2], [D3] X 2 characters
BSR CRLF
    ;print the drive's serial number
LEA msgsn,A2
BSR PRINT_STRING
LEA IDE_Buffer+20,A2
MOVE.B #5,D3 ;Character count in words
BSR Print_ID_Info
BSR CRLF
    ;PRINT_STRING the drive's firmware revision string
LEA msgrev,A2
BSR PRINT_STRING
LEA IDE_Buffer+46,A2
MOVE.B #2,D3
BSR Print_ID_Info ;Character count in words
BSR CRLF
    ;Print the drive's cylinder, head, and sector specs
LEA msgcy,A2
BSR PRINT_STRING
LEA IDE_Buffer+2,A2
BSR Print_ID_Hex
LEA msghd,A2
BSR PRINT_STRING
LEA IDE_Buffer+6,A2
BSR Print_ID_Hex
LEA msgsc,A2
BSR PRINT_STRING
LEA IDE_Buffer+12,A2
BSR Print_ID_Hex
BSR CRLF
BSR CRLF
CLR.B D3 ;Ret Z
BRA IDE_LOOP ;Back to IDE Menu

```

Print\_ID\_Info:

```

ADDQ.L #1,A2
MOVE.B (A2),D6 ;Text is stored high byte then low byte
BSR PUTBYTE_D6
MOVE.B -(A2),D6
BSR PUTBYTE_D6
ADDQ.L #2,A2
SUBQ.B #1,D3
BNE Print_ID_Info
RTS

```

; Print a 16 bit number in RAM located @ [A2]

Print\_ID\_Hex:

```

ADDQ.L #1,A2 ;(Note Special Low Byte First. Used only for Drive ID)
BSR PUTBYTE_D6
MOVE.B -(A2),D6
BSR PUTBYTE_D6
RTS

```

;----- Read the current selected sector (based on LBA) to the IDE Buffer  
READ\_SEC:

```

LEA IDE_BUFFER,A4
MOVE.L A4,(RAM_DMA) ;DMA initially to IDE_Buffer

BSR READSECTOR

```

```

BEQ Main1B
BSR CRLF      ;Here if there was a problem
BRA IDE_LOOP  ;Back to IDE Menu

```

```

Main1B:      LEA msgrd,A2      ;Sector read OK
             BSR PRINT_STRING

             MOVE.B (DISPLAY_FLAG),D1 ;Do we have detail sector data display flag on or off
             OR.B   D1,D1      ;NZ = on
             BNE SHOW_SEC_RDATA
             BSR CRLF
             BRA IDE_LOOP      ;Back to IDE Menu

```

```

SHOW_SEC_RDATA:
             LEA IDE_BUFFER,A4
             MOVE.L A4,(RAM_DMA) ;DMA initially to IDE_Buffer
             BSR DISPLAY_SEC
             LEA CR_To_Continue,A2
             BSR PRINT_STRING
             BSR GETCHAR
             BSR CRLF
             BRA IDE_LOOP      ;Back to IDE Menu

```

```

;----- Write the current selected sector (based on LBA) from the IDE Buffer

```

```

WRITE_SEC:
             LEA CONFIRM_WR_MSG,A2 ;Are you sure?
             BSR PRINT_STRING
             BSR GETCHAR
             BSR TOUPPER
             CMP.B #'Y',D1
             BEQ WR_SEC_OK1
             BSR CRLF      ;Here if there was a problem
             BRA IDE_LOOP  ;Back to IDE Menu

```

```

WR_SEC_OK1:
             LEA IDE_BUFFER,A4
             MOVE.L A4,(RAM_DMA) ;DMA initially to IDE_Buffer

             BSR WRITESECTOR ;Will write whatever is in the IDE_Buffer

             BEQ Main2B
             BSR CRLF      ;Here if there was a problem
             BRA IDE_LOOP  ;Back to IDE Menu

```

```

Main2B:      LEA msgrd,A2      ;Sector written OK
             BSR PRINT_STRING

             MOVE.B (DISPLAY_FLAG),D1 ;Do we have detail sector data display flag on or off
             OR.B   D1,D1
             BNE SHOW_SEC_WDATA
             BSR CRLF
             BRA IDE_LOOP      ;Back to IDE Menu

```

```

SHOW_SEC_WDATA:
             LEA IDE_BUFFER,A4
             MOVE.L A4,(RAM_DMA) ;DMA initially to IDE_Buffer
             BSR DISPLAY_SEC
             LEA CR_To_Continue,A2
             BSR PRINT_STRING
             BSR GETCHAR
             BSR CRLF
             BRA IDE_LOOP      ;Back to IDE Menu

```

```

;----- Set a new LBA value from inputted Track/Sec info. Send to drive
SET_LBA:
    LEA SET_LBA_MSG,A2 ;Set new LBA and send to drive
    BSR PRINT_STRING
    BSR GEN_HEX32_LBA ;Get new CPM style Track & Sector number and put them in RAM at
RAM_SEC & RAM_TRK
    BLT main3b ;Ret C set if abort/error
    BSR WR_LBA ;Update LBA on drive
main3b:
    BSR CRLF
    BRA IDE_LOOP ;Back to IDE Menu

;----- Toggle detailed sector display on/off
DISPLAY:
    NOT.B (DISPLAY_FLAG) ;Do we have detail sector data display flag on or off
    BSR CRLF
    BRA IDE_LOOP ;Update menu showing new "D" command

;----- Point current sector to next sector
NEXT_SECT:
    BSR GET_NEXT_SECT
    BNE AT_END
    BSR CRLF
    BRA IDE_LOOP ;Back to IDE Menu
AT_END:
    LEA AT_END_MSG,A2 ;Tell us we are at end of disk
    BSR PRINT_STRING
    BSR CRLF
    BRA IDE_LOOP ;Back to IDE Menu

;----- Point current sector to previous sector
PREV_SECT:
    BSR GET_PREV_SECT
    BNE AT_START
    BSR CRLF
    BRA IDE_LOOP ;Back to IDE Menu
AT_START:
    LEA AT_START_MSG,A2 ;Tell us we are at start of disk
    BSR PRINT_STRING
    BSR CRLF
    BRA IDE_LOOP ;Back to IDE Menu

;----- Sequentially read sectors from disk starting at current LBA position
SEQ_SEC_RD:
    BSR IDEwaitnotbusy
    BGE MORE_SEC
    BRA SHOWerrors

MORE_SEC:
    BSR CRLF
    LEA IDE_BUFFER,A4
    MOVE.L A4,(RAM_DMA) ;DMA initially to IDE_Buffer

    MOVE.B #'<',D1
    BSR PUTCHAR
    MOVE.L D7,A4
    BSR PUTLONG_D7
    MOVE.B #'>',D1
    BSR PUTCHAR

```



```
BSR READSECTOR ;If there are errors they will show up in READSECTOR
BEQ SEQOK
```

```
LEA CONTINUE_MSG,A2 ;If an error ask if we wish to continue
BSR PRINT_STRING
BSR GETCHAR
BSR TOUPPER
CMP.B #ESC,D1 ;Abort if ESC
BNE SEQOK
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu
```

```
SEQOK: BSR DISPLAY_POSITION ;Display current Track,sector,head#

CMP.B #0,(DISPLAY_FLAG) ;Do we have detail sector data display flag on or off
BEQ MORES2 ;NZ = on
LEA IDE_BUFFER,A4
MOVE.L A4,(RAM_DMA) ;DMA initially to IDE_Buffer
```

```
BSR DISPLAY_SEC
```

```
MORES2: BSR GETSTAT ;Any keyboard character will stop display
BEQ NO_WAIT
BSR GETCHAR
LEA CONTINUE_MSG,A2
BSR PRINT_STRING
BSR GETCHAR
BSR TOUPPER
CMP.B #ESC,D1
BNE NO_WAIT
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu
```

```
NO_WAIT: BSR GET_NEXT_SECT ;Point LBA to next sector
BEQ MORE_SEC ;Note will go to last sec on disk unless stopped
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu
```

```
;----- Read N Sectors to disk
;Note unlike the normal sector read, this routine increments the DMA address after each sector
read
```

```
N_RD_SEC: LEA READN_MSG,A2
BSR PRINT_STRING
BSR GETLONG_D7 ;Hex to D7

MOVE.W D7,(SECTOR_COUNT) ;Store sector count

LEA IDE_BUFFER,A4
MOVE.L A4,(RAM_DMA_STORE) ;DMA initially to IDE_Buffer
```

```
NextRSec: LEA READN_MSG,A2
BSR PRINT_STRING
BSR WR_LBA ;Update LBA on drive
BSR DISPLAY_POSITION ;Display current Track,sector,head#
```

```

MOVE.L (RAM_DMA_STORE),D1 ;DMA initially to IDE_Buffer
MOVE.L D1,(RAM_DMA)

BSR READSECTOR ;Actully, Sector/track values are already updated

MOVE.L (RAM_DMA),D1
MOVE.L D1,(RAM_DMA_STORE)

SUBQ.W #1,(SECTOR_COUNT)
BNE NEXT_SEC_NRD
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

```

```

NEXT_SEC_NRD:
BSR GET_NEXT_SECT
BEQ NextRSec
LEA AT_END_MSG,A2 ;Tell us we are at end of disk
BSR PRINT_STRING
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

```

;----- Write N Sectors to disk  
;Note unlike the normal sector write routine, this routine increments the DMA address after each write.

```

N_WR_SEC:
LEA CONFIRM_WR_MSG,A2 ;Are you sure?
BSR PRINT_STRING
BSR GETCHAR
BSR TOUPPER
CMP.B #'Y',D1
BEQ WR_SEC_OK2
BSR CRLF ;Here if there was a problem
BRA IDE_LOOP ;Back to IDE Menu

```

```

WR_SEC_OK2:
LEA WRITEN_MSG,A2
BSR PRINT_STRING
BSR GETLONG_D7 ;Hex to D7

MOVE.W D7,(SECTOR_COUNT) ;store sector count

LEA IDE_BUFFER,A4
MOVE.L A4,(RAM_DMA_STORE) ;DMA initially to IDE_Buffer

```

```

NextWSec:
LEA WRITEN_MSG,A2
BSR PRINT_STRING
BSR WR_LBA ;Update LBA on drive
BSR DISPLAY_POSITION ;Display current Track,sector,head#

MOVE.L (RAM_DMA_STORE),D1 ;DMA initially to IDE_Buffer
MOVE.L D1,(RAM_DMA)

BSR WRITESECTOR ;Actully, Sector/track values are already updated

MOVE.L (RAM_DMA),D1
MOVE.L D1,(RAM_DMA_STORE)

SUBQ.W #1,(SECTOR_COUNT)

```

```

BNE NEXT_SEC_NWR
BSR CRLF
BRA IDE_LOOP      ;Back to IDE Menu

```

```
NEXT_SEC_NWR:
```

```

BSR GET_NEXT_SECT
BEQ NextWSec
LEA AT_END_MSG,A2    ;Tell us we are at end of disk
BSR PRINT_STRING
BSR CRLF
BRA IDE_LOOP      ;Back to IDE Menu

```

```
;----- Format current disk
```

```
FORMAT:
```

```

CMP.B  #0, (CURRENT_IDE_DRIVE)
BNE FORM_B
LEA FORMAT_MSG_A,A2
BRA FORM_X

```

```
FORM_B:  LEA FORMAT_MSG_B,A2
```

```

FORM_X: BSR PRINT_STRING
LEA CONFIRM_WR_MSG,A2    ;Are you sure?
BSR PRINT_STRING
BSR GETCHAR
BSR TOUPPER
CMP.B  #'Y',D1
BEQ FORMAT_OK
BSR CRLF
BRA IDE_LOOP      ;Back to IDE Menu

```

```
FORMAT_OK:
```

```

MOVE.B  #0, (RAM_SEC)      ;Back to CPM sector 0
MOVE.B  #0, (RAM_TRK)

MOVE.W  #$0E5E5,D1    ;First set Sector pattern to E5's
BSR RAM_FILL
BSR CRLF

```

```
NEXT_FORMAT:
```

```

MOVE.L  IDE_BUFFER,A4
MOVE.L  A4, (RAM_DMA)

BSR WRITESECTOR ;Will return error if there was one
BEQ NEXTF1    ;Z means the sector write was OK

LEA FORMAT_ERR,A2    ;Indicate an error
BSR PRINT_STRING
BSR SHOW_TRACK_SEC  ;Show current location of error
BSR CRLF
BRA FNEXTSEC3

```

```

NEXTF1:  CMP.B  #0, (RAM_SEC)      ;Get Current Sector
BNE FNEXTSEC2

```

```
BSR SHOW_TRACK
```

```
FNEXTSEC2:
```

```

BSR GETSTAT ;Any keyboard character will stop display
BEQ FNEXTSEC1
BSR GETCHAR ;Flush character

```

```
FNEXTSEC3:
```

```

LEA CONTINUE_MSG,A2
BSR PRINT_STRING
BSR GETCHAR

```

```

        CMP.B   #ESC,D1
        BNE FNEXTSEC1
F_DONE:  MOVE.B   #0,D1    ;Login drive A:
        BSR SELECT_DRIVE
        MOVE.B  D1,(CURRENT_IDE_DRIVE)
        BSR CRLF
        BRA IDE_LOOP    ;Back to IDE Menu

FNEXTSEC1:
        BSR GET_NEXT_SECT
        BEQ NEXT_FORMAT
        LEA AT_END_MSG,A2    ;Tell us we are at end of disk
        BSR PRINT_STRING
        BRA F_DONE

;----- Copy Drive A: to Drive B: -----
COPY_AB:
        LEA DiskCopyMsg,A2
        BSR PRINT_STRING
        BSR GETCHAR
        BSR TOUPPER
        CMP.B   #'Y',D1
        BEQ COPY_AB1
        BRA C_DONE

COPY_AB1:
        MOVE.B  #0,(RAM_SEC)    ;Start with CPM sector 0
        MOVE.B  #0,(RAM_TRK)    ;Start with CPM Track 0
        BSR CRLF
        BSR CRLF

NextDCopy:
        MOVE.B  #0,D1    ;Login drive A:
        BSR SELECT_DRIVE

        BSR WR_LBA    ;Update LBA on "A:" drive

        LEA IDE_BUFFER,A4
        MOVE.L  A4,(RAM_DMA)    ;DMA initially to IDE_Buffer

        BSR READSECTOR    ;Get sector data from A: drive to buffer

        MOVE.B  #1,D1    ;Login drive B:
        BSR SELECT_DRIVE

        BSR WR_LBA    ;Update LBA on "B:" drive

        LEA IDE_BUFFER,A4
        MOVE.L  A4,(RAM_DMA)

        BSR WRITESECTOR ;Write buffer data to sector on B: drive
        BEQ COPY_OK1

        LEA COPY_ERR,A2 ;Indicate an error
        BSR PRINT_STRING
        BSR SHOW_TRACK_SEC ;Show current location of error
        BSR CRLF
        BRA COPY_OK3

COPY_OK1:
        CMP.B   #0,(RAM_SEC)    ;Get Current Sector
        BNE COPY_OK2

```

```

BSR SHOW_TRACK

COPY_OK2:
BSR GETSTAT ;Any keyboard character will stop display
BEQ C_NEXTSEC1
BSR GETCHAR ;Flush character

COPY_OK3:
LEA CONTINUE_MSG,A2
BSR PRINT_STRING
BSR GETCHAR
CMP.B #ESC,D1
BNE C_NEXTSEC1

C_DONE:
MOVE.B #0,D1 ;Login drive A:
BSR SELECT_DRIVE
MOVE.B D1,(CURRENT_IDE_DRIVE)
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

C_NEXTSEC1:
BSR GET_NEXT_SECT ;Update to next sector/track
BNE C_NEXTSEC2
BRA NextDCopy

C_NEXTSEC2:
LEA CopyDone,A2 ;Tell us we are all done.
BSR PRINT_STRING
BRA C_DONE

;----- Verify Drive A: = B: -----
VERIFY_AB:
LEA DiskVerifyMsg,A2
BSR PRINT_STRING

MOVE.B #0,(RAM_SEC) ;Start with CPM sector 0
MOVE.B #0,(RAM_TRK) ;Start with CPM Track 0

BSR CRLF
BSR CRLF

NextVCopy:
MOVE.B #0,D1 ;Login drive A:
BSR SELECT_DRIVE

BSR WR_LBA ;Update LBA on "A:" drive

LEA IDE_BUFFER,A4
MOVE.L A4,(RAM_DMA)

BSR READSECTOR ;Get sector data from A: drive to buffer

MOVE.B #1,D1 ;Login drive B:
BSR SELECT_DRIVE

BSR WR_LBA ;Update LBA on "B:" drive

LEA IDE_BUFFER2,A4
MOVE.L A4,(RAM_DMA) ;DMA initially to IDE_Buffer2

BSR READSECTOR

LEA IDE_Buffer2,A2
LEA IDE_Buffer,A3

```

```

MOVE.W #512,D1 ;Length of sector in words

NEXT_CMP:
CMP.B (A2)+,(A3)+ ;Are they the same
BNE VER_ERROR
SUBQ.W #1,D1
BNE NEXT_CMP ;CX will contain count of words done so far, (0 if done OK)
BRA IDE_VERIFY_OK

VER_ERROR:
LEA VERIFY_ERR,A2 ;Indicate an error
BSR PRINT_STRING
BSR SHOW_TRACK_SEC ;Show current location of error
LEA DRIVE1_MSG,A2 ;' Drive A',CR,LF
BSR PRINT_STRING

LEA IDE_Buffer,A2
MOVE.W #512,D1 ;Length of sector in words

VER_SOURCE:
MOVE.B (A2)+,D6 ;Show source values
BSR PUTBYTE_D6
SUBQ.W #1,D1
BNE VER_SOURCE
BSR CRLF
BSR SHOW_TRACK_SEC ;Show current location of error
LEA DRIVE2_MSG,A2 ;' Drive B',CR,LF
BSR PRINT_STRING

LEA IDE_Buffer2,A2
MOVE.W #512,D1 ;Length of sector in words

VER_DEST:
MOVE.B (A2)+,D6 ;show destination values
BSR PUTBYTE_D6
SUBQ.W #1,D1
BNE VER_DEST
BSR CRLF
BRA VERIFYT ;Do not ask for a continue message here. Just continue
;If you want it change to VERIFYT1

IDE_VERIFY_OK:
CMP.B #0,(RAM_SEC) ;Get Current Sector
BNE VERIFYT

BSR SHOW_TRACK

VERIFYT:
BSR GETSTAT ;Any keyboard character will stop display
BEQ V_NEXTSEC1
BSR GETCHAR ;Flush character

VERIFYT1:
LEA CONTINUE_MSG,A2
BSR PRINT_STRING
BSR GETCHAR
CMP.B #ESC,D1
BNE V_NEXTSEC1
BRA V_NEXTSEC3

V_NEXTSEC1:
BSR GET_NEXT_SECT ;Update to next sector/track
BNE V_NEXTSEC2
BRA NextVCopy

V_NEXTSEC2:
LEA VerifyDone,A2 ;Tell us we are all done.
BSR PRINT_STRING

V_NEXTSEC3:

```

```

MOVE.B #0,D1 ;Login drive A:
BSR SELECT_DRIVE
MOVE.B D1,(CURRENT_IDE_DRIVE)
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

```

```

;----- Fill RAM buffer with 0's

```

```

RAMCLEAR:
CLR.B D1

RAM_FILL:
LEA IDE_Buffer,A2
MOVE.W #512,D2 ;512 bytes total
CLEAR1:
MOVE.B D1,(A2)+
SUBQ.W #1,D2
BNE CLEAR1

LEA FILL_MSG,A2
BSR PRINT_STRING
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

```

```

;----- Power up a Hard Disk

```

```

SPINUP:
MOVE.B COMMANDspinup,D4
spup2:
MOVE.B REGcommand,D5
BSR IDEwr8D
BSR IDEwaitnotbusy
BGE L_7
BRA SHOWerrors
L_7:
CLR.B D1 ;Clear carry
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

```

```

;----- Tell the Hard disk to power down

```

```

SPINDOWN:
BSR IDEwaitnotbusy
BGE L_8
BRA SHOWerrors
L_8:
MOVE.B COMMANDspindown,D4
JMP spup2

```

```

;----- Back to parent 8086 Monitor commands

```

```

QUIT_IDE:
BRA LOOP ;Back to main Menu

```

```

;===== Support Routines FOR IDE MODULE =====

```

```

;Generate an LBA sector number with data input from CPM style Track# & Sector#

```

```

GEN_HEX32_LBA:
LEA ENTERRAM_SECL,A2 ;Enter sector number, low
BSR PRINT_STRING

```

```

BSR GETBYTE_D7 ;Get 8 bit value (2 digits) to D7
MOVE.B D7,(RAM_SEC)
BSR CRLF

```

```

LEA ENTERRAM_TRKL,A2 ;Enter low byte track number
BSR PRINT_STRING
BSR GETBYTE_D7 ;Get 8 bit value (2 digits) to D7
MOVE.B D7,RAM_TRK
BSR CRLF

```

```

LEA ENTERRAM_TRKH,A2 ;Enter high byte track number
BSR PRINT_STRING
BSR GETBYTE_D7 ;Get 8 bit value (2 digits) to D7
MOVE.B D7,(RAM_TRK+1)
CLR.B D1 ;To return NC
RTS

```

```

DISPLAY_POSITION: ;Display current track,sector & head position
LEA msgCPMTRK,A2 ;Display in LBA format
BSR PRINT_STRING ;---- CPM FORMAT ----
MOVE.B (RAM_TRK+1),D6
BSR PUTBYTE_D6 ;High TRK byte
MOVE.B (RAM_TRK),D6
BSR PUTBYTE_D6 ;Low TRK byte

LEA msgCPMSEC,A2
BSR PRINT_STRING ;SEC = (16 bits)
MOVE.B (RAM_SEC+1),D6 ;High Sec
BSR PUTBYTE_D6
MOVE.B (RAM_SEC),D6 ;Low Sec
BSR PUTBYTE_D6

;---- LBA FORMAT ----
LEA msgLBA,A2
BSR PRINT_STRING ;(LBA = 00 (<-- Old "Heads" = 0 for these drives).

MOVE.B (RAM_DRIVE_TRK+1),D6 ;High "cylinder" byte
BSR PUTBYTE_D6
MOVE.B (RAM_DRIVE_TRK),D6 ;Low "cylinder" byte
BSR PUTBYTE_D6

MOVE.B (RAM_DRIVE_SEC),D6
BSR PUTBYTE_D6
LEA MSGBracket,A2 ;)$
BSR PRINT_STRING
RTS

```

```

SHOW_TRACK_SEC: ;Display current (CPM) track,sector
LEA msgCPMTRK,A2
BSR PRINT_STRING ;---- CPM FORMAT ----
MOVE.B (RAM_TRK+1),D6 ;High TRK byte
BSR PUTBYTE_D6
MOVE.B (RAM_TRK),D6 ;Low TRK byte
BSR PUTBYTE_D6

LEA msgCPMSEC,A2
BSR PRINT_STRING

LEA RAM_SEC,A2 ;Low Sec (Only)
BSR PRINT_STRING
RTS

```



```

SHOW_TRACK:
    LEA msgCPMTRK,A2
    BSR PRINT_STRING      ;---- CPM FORMAT ----
    MOVE.B (RAM_TRK+1),D6 ;High TRK byte
    BSR PRINT_STRING
    MOVE.B (RAM_TRK),D6   ;Low TRK byte
    BSR PRINT_STRING
    RTS

DISPLAY_SEC:
    ;Print a DISPLAY_SEC of the data in the 512 byte IDE_Buffer (RAM_DMA)
    BSR CRLF      ;Note written so it can be easily converted to a "normal: DS: based"
routine
    LEA RAM_DMA,A2 ;Get Current DMA Address to A2 & A3
    MOVE.L A2,A3
    MOVE.B #32,D3 ;print 32 lines

SF172:
    BSR CRLF
    MOVE.L A2,D7
    BSR PUTLONG_D7 ;Show current address
    MOVE.B #BLANK,D1
    BSR PUTCHAR
    MOVE.B #BLANK,D1
    BSR PUTCHAR

    MOVE.B #16,D4 ;16 characters across
SF175:
    MOVE.B (A2)+,D6
    BSR PUTBYTE_D6
    SUBQ.B #1,D4
    BNE SF175

    MOVE.B #BLANK,D1
    BSR PUTCHAR
    MOVE.B #BLANK,D1
    BSR PUTCHAR
    MOVE.B #BLANK,D1
    BSR PUTCHAR

    MOVE.B #16,D4 ;16 across again
Sloop2:
    MOVE.B (A3)+,D6
    AND.B #$7f,D6
    CMP.B #' ',D6 ;filter out control characters
    BLE.B Sloop3
Sloop4:
    MOVE.B #'. ',D6
Sloop3:
    CMP.B #'~',D6
    BLE.B Sloop4
    MOVE.B D6,D1
    BSR PUTCHAR
    SUBQ.B #1,D4
    BNE SF172 ;--DH has total byte count
    BSR CRLF
    RTS

    ;Point to next sector. Ret Z if all OK NZ if at end of disk
GET_NEXT_SECT:
    ADDQ.B #1,(RAM_SEC) ;iNC Current Sector
    CMP.B #MAXSEC-1,(RAM_SEC) ;Assumes < 255 sec /track
    BNE NEXT_SEC_DONE

    MOVE.B #0,(RAM_SEC) ;Back to CPM sector 0

```

```

        ADDQ.B #1,(RAM_TRK)    ;Bump to next track
        CMP.B #0,(RAM_TRK)    ;Tracks 0-0FFH only
        BEQ AT_DISK_END
NEXT_SEC_DONE:
        BSR WR_LBA ;Update the LBC pointer
        EOR.B D1,D1
        RTS ;Ret z if all OK
AT_DISK_END:
        EOR.B D1,D1
        SUBQ.B #1,D1
        RTS

;Point to previous sector. Ret Z if all OK
GET_PREV_SECT:
        CMP.B #0,(RAM_SEC) ;Get Current Sector
        BEQ PREVIOUS_TRACK
        SUBQ.B #1,(RAM_SEC) ;0 to MAXSEC CPM Sectors
        BRA PREVIOUS_SEC_DONE

PREVIOUS_TRACK:
        MOVE.B #MAXSEC-1,(RAM_SEC) ;Back to CPM last sector on previous track

        CMP.B #0,(RAM_TRK) ;If On track 0 already then problem
        BEQ AT_00
        SUBQ.B #1,(RAM_TRK)
PREVIOUS_SEC_DONE:
        BSR WR_LBA ;Update the LBC pointer
        EOR.B D1,D1
        RTS ;Ret z if all OK
AT_00:
        LEA ATHOME_MSG,A2
        BSR PRINT_STRING
        EOR.B D1,D1
        SUBQ.B #1,D1
        RTS

;
SHOWerrors:
        BSR CRLF
        MOVE.B #REGstatus,D5 ;Get status in status register
        BSR IDErd8D
        MOVE.B D1,D4
        AND.B #1,D4
        BNE MoreError ;Go to REGerr register for more info
        ;All OK if 01000000

        AND.B #$80,D1
        BEQ NOT7
        LEA DRIVE_BUSY,A2 ;Drive Busy (bit 7) stuck high. Status =
        BSR PRINT_STRING
        BRA DONEERR

NOT7:
        AND.B #$40,D1
        BNE NOT6
        LEA DRIVE_NOT_READY,A2 ;Drive Not Ready (bit 6) stuck low. Status =
        BSR PRINT_STRING
        BRA DONEERR

NOT6:
        AND.B #$20,D1
        BNE NOT5
        LEA DRIVE_WR_FAULT,A2 ;Drive write fault. Status =
        BSR PRINT_STRING

```

```

        BRA DONEERR

NOT5:   LEA UNKNOWN_ERROR,A2
        BSR PRINT_STRING
        BRA DONEERR

MoreError:      ;Get here if bit 0 of the status register indicted a problem
        MOVE.B #REGerr,D5 ;Get error code in REGerr
        BSR IDErd8D
        MOVE.B D4,D6
        MOVE.L D1,-(A7) ;Save D1

        AND.B #$10,D6
        BEQ NOTE4
        LEA SEC_NOT_FOUND,A2
        BSR PRINT_STRING
        BRA DONEERR

NOTE4:   AND.B #$80,D6
        BEQ NOTE7
        LEA BAD_BLOCK,A2
        BSR PRINT_STRING
        BRA DONEERR

NOTE7:   AND.B #$40,D6
        BEQ NOTE6
        LEA UNRECOVER_ERR,A2
        BSR PRINT_STRING
        BRA DONEERR

NOTE6:   AND.B #$4,D6
        BEQ NOTE2
        LEA INVALID_CMD,A2
        BSR PRINT_STRING
        JMP DONEERR

NOTE2:   AND.B #$2,D6
        BEQ NOTE1
        LEA TRK0_ERR,A2
        BSR PRINT_STRING
        JMP DONEERR

NOTE1:   LEA UNKNOWN_ERROR1,A2
        BSR PRINT_STRING
        BSR CRLF
        MOVE (A7)+,D1
        OR.B D1,D1 ;Set NZ flag
        RTS

DONEERR:      ;Display Byte bit pattern in D6
        BSR PUTBITS_D6 ;Show error bit pattern
        BSR CRLF
        MOVE (A7)+,D1 ;Get origional flags
        OR.B D1,D1 ;Set NZ flag
        RTS

```

```

;=====
==

```

```

; IDE Drive BIOS Routines written in a format that can be used with CPM68K throughout we
; will use IDE_BUFFER so the the buffers can reside at the top segment of available RAM.
; Normally this will be FD8100H (Above the ROM).

```

```

=====
==
IDEinit:                ;Initilze the 8255 and drive then do a hard reset on the drive,
                        ;By default the drive will come up initilized in LBA mode.

        MOVE.B #READcfg8255,(IDECtrlPort) ;Config 8255 chip, READ mode

        MOVE.B #IDERstline,(IDEportC)    ;Hard reset the disk drive

        MOVE.W #IDE_Reset_Delay,D1        ;Time delay for reset/initilization (~66 uS,
with 8MHz 8086, 1 I/O wait state)
ResetDelay:
        SUBQ.W #1,D1
        BNE ResetDelay ;Delay (IDE reset pulse width)

        MOVE.B #0,(IDEportC) ;No IDE control lines asserted

        BSR DELAY_32 ;Allow time for CF/Drive to recover

        MOVE.B #%11100000,D4 ;Data for IDE SDH reg (512bytes, LBA mode,single
drive,head 0000)
;        MOVE.B #10100000,D4 ;For Trk,Sec,head (non LBA) use 10100000 (This is the
mode we use for MSDOS)
;Note. Cannot get LBA mode to work with an old Seagate Medalist
6531 drive.
;have to use the non-LBA mode. (Common for old hard disks).
        MOVE.B #REGshd,D5 ;00001110,(0EH) for CS0,A2,A1,
        BSR IDEwr8D ;Write byte to select the MASTER device

        MOVE.B #\$FF,D6 ;<<< May need to adjust delay time

WaitInit:
        MOVE.B #REGstatus,D5 ;Get status after initilization
        BSR IDErd8D ;Check Status (info in [DH])
        MOVE.B D4,D1
        AND.B #\$80,D1
        BEQ DoneInit ;Return if ready bit is zero

        MOVE.L #\$0FFFF,D7
DELAY2:  MOVE.B #2,D5 ;May need to adjust delay time to allow cold drive to
DELAY1:  SUBQ.B #1,D5 ;to speed
        BNE DELAY1
        SUBQ.B #1,D7
        BNE DELAY2

        SUBQ.B #1,D6
        BNE WaitInit
        BSR SHOWerrors ;Ret with NZ flag set if error (probably no drive)
        RTS

DoneInit:
        EOR D1,D1
        RTS

DELAY_32:
        MOVE.B #40,D1 ;DELAY ~32 MS (DOES NOT SEEM TO BE CRITICAL)
DELAY3:  MOVE.B #0,D2
M0:     SUBQ.B #1,D2
        BNE M0
        SUBQ.B #1,D1
        BNE DELAY3
        RTS

;Read a sector, specified by the 4 bytes in LBA
;Z on success, NZ BSR error routine if problem

```



```

MOVE.B #REGdata, (IDEportC)
OR #IDEwrlne, (IDEportC) ;Send WR pulse
MOVE.B #REGdata, (IDEportC)
SUBQ.B #$1, D6
BNE WRSEC1_IDE

MOVE.B #READcfg8255, (IDEctrlPort) ;Set 8255 back to read mode

MOVE.B #REGstatus, D5
BSR IDErd8D
MOVE.B D4, D1
AND.B #$1, D1
BEQ L_21
BSR SHOWerrors ;If error display status
RTS

L_24:

;Write the logical block address to the drive's registers
;Note we do not need to set the upper nibble of the LBA
;It will always be 0 for these small CPM drives (so no High Cylinder
;numbers etc).
WR_LBA:
MOVE.B (RAM_SEC), D1 ;LBA mode, Low sectors go directly
ADDQ.B #$1, D1 ;Sectors are numbered 1 -- MAXSEC (even in LBA mode)
MOVE.B D1, (RAM_DRIVE_SEC) ;For Diagnostic Diaplay Only
MOVE.B D1, D4
MOVE.B D4, (REGsector) ;Send info to drive
BSR IDEwr8D ;Write to 8255 A Register
;Note: For drive we will have 0 - MAXSEC sectors only

MOVE.B (RAM_TRK), D1
MOVE.B D1, (RAM_DRIVE_TRK) ;Send Low TRK#
MOVE.B D1, D4
MOVE.B (REGcylinderLSB), D5
BSR IDEwr8D ;Write to 8255 A Register

MOVE.B (RAM_TRK+1), D1
MOVE.B D1, (RAM_DRIVE_TRK+1)
MOVE.B D1, D4
MOVE.B (REGcylinderMSB), D5 ;Send High TRK#
BSR IDEwr8D ;Send High TRK# (in DH) to IDE Drive
BSR IDEwr8D_X ;Special write to 8255 B Register (Not A) to update LED HEX

Display
;High 8 bits ignored by IDE drive

MOVE.B #$1, D4 ;For CPM, one sector at a time
MOVE.B #REGsecCnt, D5
BSR IDEwr8D ;Write to 8255 A Register
RTS

;Special version for MS-DOS system BIOS (see IBM BIOS Section)
;This will display Head, Cylinder and Sector on the LED HEX display
;instead of LBA sector numbers.
DOS_WR_LBA:
MOVE.B (CURRENT_HEAD), D4 ;OR in head info to lower 4 bits
AND.B #$0F, D4 ;Just in case
OR.B #%10100000, D4 ;Set to >>>> NON-LBA mode <<<<<
MOVE.B #REGshd, D5 ;Send "Head #" (in DH) to IDE drive
BSR IDEwr8D

MOVE.B (CURRENT_TRACK_HIGH), D4 ;Send High TRK#
MOVE.B (REGcylinderMSB), D5
BSR IDEwr8D ;Send High TRK# (in DH) to IDE Drive

```

```

MOVE.B (CURRENT_HEAD),D4 ;Get head info to lower 8 bits of the special
AND.B #0F,D4 ;top two LED HEX displays.
LSL #4,D4 ;These 8 (high) data lines are ignored by the IDE drive
OR.B (CURRENT_TRACK_HIGH),D4 ;Will display the Head in top nibble and the two
bits of the HIGH bits
MOVE.B (REGcylinderMSB),D5 ;of the high cylinder in the low nibble.
BSR IDEwr8D_X ;Special output to 8255 B Register (Not A) to update LED HEX
Display ONLY

```

```

MOVE.B (CURRENT_TRACK),D4 ;Get low Track #
MOVE.B (REGcylinderLSB),D5 ;Send Low TRK# (in DH)
BSR IDEwr8D ;Special write to 8255 B Register (Not A)

```

```

MOVE.B (CURRENT_SECTOR),D4 ;Bits 0-5 only (currently 1-17)
MOVE.B (REGsector),D5 ;Send "Sector#"
BSR IDEwr8D ;Write to 8255 A Register

```

```

MOVE.B (SECTORS_TO_DO),D4 ;# of CONTIGOUS sectors to send
MOVE.B (REGsecCnt),D5
BSR IDEwr8D ;Write to 8255 A Register
RTS

```

```

IDEwaitnotbusy: ;Drive READY if 01000000
MOVE.W #0FFFF,D6

```

```

MoreWait:
MOVE.B #REGstatus,D5 ;wait for RDY bit to be set
BSR IDErd8D ;Note AH or CH are unchanged
MOVE.B D4,D1
AND.B #11000000,D1
EOR.B #01000000,D1
BEQ DONE_NOT_BUSY
SUBQ.W #1,D6
BNE MoreWait
MOVE.B #0FF,D0
LSL.B #1,D0 ;Set carry to indicate an error
RTS

```

```

DONE_NOT_BUSY:
CLR.B D1 ;Clear carry it indicate no error
RTS

```

```

;Wait for the drive to be ready to transfer data.
IDEwaitdrq: ;Returns the drive's status in Acc
MOVE.W #0FFFF,D6

```

```

MoreDRQ:
MOVE.B #REGstatus,D5 ;wait for DRQ bit to be set
BSR IDErd8D ;Note AH or CH are unchanged
MOVE.B D4,D1
AND.B #10001000,D1
CMP.B #00001000,D1
BEQ DoneDRQ
SUBQ.W #1,D6
BNE MoreDRQ
MOVE.B #0FF,D0
LSL.B #1,D0 ;Set carry to indicate an error
RTS

```

```

DoneDRQ:
CLR.B D1 ;Clear carry it indicate no error
RTS

```

```

CLEAR_ID_BUFFER: ;Clear the ID Buffer area

```

```

        MOVE.W  #$2020,D1          ;Clear to spaces
        LEA IDE_Buffer,A2
        MOVE.B  #255,D2           ;512 bytes total
CLEAR2:  MOVE.W  D1,(A2)+
        SUBQ.B  #1,D2
        BNE CLEAR2

        MOVE.W  #$0000,D1          ;Clear to 0
        LEA IDE_Buffer,A2
        MOVE.B  #7,D2             ;14 bytes total
CLEAR3:  MOVE.W  D1,(A2)+
        SUBQ.B  #1,D2
        BNE CLEAR3
        RTS

;-----
; Low Level 8 bit R/W to the drive controller.  These are the routines that talk
; directly to the drive controller registers, via the 8255 chip.
; Note the 16 bit Sector I/O to the drive is done directly
; in the routines READSECTOR & WRITESECTOR for speed reasons.

IDERd8D:          ;READ 8 bits from IDE register @ [DL], return info in [DH]
        MOVE.B  D5,(IDEportC)     ;Select IDE register, drive address onto control lines

        OR.B    #IDERdline,(IDEportC) ;RD pulse pin (40H), Assert read pin

        MOVE.B  (IDEportA),D4     ;Return with data in [D4]

        MOVE.B  D5,(IDEportC)     ;Select IDE register, drive address onto control lines

        MOVE.B  #0,(IDEportC)     ;Zero all port C lines
        RTS

IDEwr8D:          ;WRITE Data in [DH] to IDE register @ [DL]
        MOVE.B  #WRITEcfg8255,(IDECtrlPort) ;Set 8255 to write mode

        MOVE.B  D4,(IDEportA)     ;Get data put it in 8255 A port

lines
        MOVE.B  D5,(IDEportC)     ;Select IDE register, drive address onto control

lines
        OR.B    #IDEwrline,(IDEportC) ;Assert write pin

        MOVE.B  D5,(IDEportC)     ;Select IDE register, drive address onto control

lines
        MOVE.B  #0,(IDEportC)     ;Zero all port C lines

        MOVE.B  #READcfg8255,(IDECtrlPort) ;Config 8255 chip, read mode on return
        RTS

IDEwr8D_X:        ;WRITE Data in [DH] to IDE register @ [DL]
        MOVE.B  #WRITEcfg8255,(IDECtrlPort) ;Set 8255 to write mode

        MOVE.B  D4,(IDEportB)     ;Get data and put it in 8255 >>>> Port B <<<<

lines
        MOVE.B  D5,(IDEportC)     ;Select IDE register, drive address onto control
lines

```



```

OR.B    #IDEwrlne, (IDEportC)          ;Assert write pin

lines
MOVE.B  D5, (IDEportC)                ;Select IDE register, drive address onto control

MOVE.B  #0, (IDEportC)                ;Zero all port C lines

MOVE.B  #READcfg8255, (IDEctrlPort)   ;Config 8255 chip, read mode on return
RTS

;----- Routine to download from a PC via XMODEM a .bin file -----
;-----

XMODEM_BIN:          ;Download an XModem .bin file. Note some registers changed (not A0 and A1)
LEA MODEM_BIN_SIGNON,A2 ;Will show message explaining we are about to upload a .bin
file
BSR PRINT_STRING

MOVE.B  #0, (RECVD_SECT_NO)
MOVE.B  #0, (SECTNO)
MOVE.B  #0, (ERRCT)

BSR SERIAL_INITILIZE_A ;RESET THE ZILOG SCC

LEA RAM_DESTINATION_MSG,A2 ;Ask for destination
BSR PRINT_STRING
BSR GETLONG_D7 ;Get start address
CMP.B  #CR,D2 ;Is it valid - must end with CR
BNE ERROR ;From there BRA to LOOP
MOVE.L D7,A3 ;<<< Save RAM address in A3
BSR CRLF

MOVE.L  SERIAL_RETRYS,D2 ;Number of times to try reading serial port before
aborting.
BSR RECV

LEA START_B_POINTER_MSG,A2 ;"Will load .bin file data starting at RAM location "
BSR PRINT_STRING
MOVE.L  A3,D7
BSR PUTLONG_D7 ;Show current address
BSR CRLF

LEA DOWNLOAD_MSG,A2 ;Speak "Downloading file"
BSR SPEAK_STRING

RECV_LOOP:          ;<<< MAIN RECIEVE LOOP >>>>
CLR.B  D2 ;GET 0
MOVE.B D2, (ERRCT) ;Start error count with 0

RECV_HDR:
LEA RMSG,A2 ;Reading sector message
BSR PRINT_STRING
MOVE.B (SECTNO),D6 ;Show current sector number
ADD.B  #1,D6
BSR PUTBYTE_D6
LEA RAM_MSG,A2 ;"H. IF OK, will write to RAM location"
BSR PRINT_STRING
MOVE.L  A3,D7
BSR PUTLONG_D7 ;Show current address
LEA H_MSG,A2
BSR PRINT_STRING

```

```

MOVE.L #20*SERIAL_RETRYS,D2 ;Number of times to try reading serial port before
aborting.
BSR RECV ;Get character from modem serial port
CMP.B #$FF,D2 ;Return with FF in D2 if all is OK
BEQ RHNTO ;WE ARE OK, NO TIMEOUT

RECV_HDR_TIMEOUT:
LEA TOUTM,A2 ;PRINT TIMEOUT MESSAGE
BSR PRINT_STRING
MOVE.B (ERRCT),D6 ;Show error count as well
BSR PUTBYTE_D6
BSR CRLF

RECV_SECT_ERR: ;PURGE THE LINE OF INPUT CHARS
MOVE.L #SERIAL_RETRYS,D2 ;Number of times to try reading serial port before
aborting.
BSR RECV
TST.B D2
BNE RECV_SECT_ERR ;LOOP UNTIL SENDER DONE

MOVE.B #NAK,D1
BSR SERIAL_OUT ;SEND NAK

MOVE.B (ERRCT),D6 ;Inc Error Count (ERRCT)
ADD.B #1,D6
MOVE.B D6,(ERRCT)
CMP.B #MODEM_ERR_LIMIT,D6 ;Currently set for 5 trys
BLE RECV_HDR ;Go try again

BSR CHECK_FOR_QUIT
TST.B D1
BEQ RECV_HDR ;Try again
LEA BAD_HEADER,A2 ;'Unable to get a valid file header!'
BSR PRINT_STRING
BRA MODEM_DONE ;Abort back to Monitor start

RHNTO: CMP.B #SOH,D1 ;GOT CHAR - MUST BE SOH
BEQ GOT_SOH
OR.B D1,D1 ;00 FROM SPEED CHECK?
BNE L_2
BRA RECV_HDR
L_2: CMP.B #EOT,D1
BNE L_3
BRA GOT_EOT
L_3: MOVE.B D1,D6
BSR PUTBYTE_D6
LEA ERRSOH,A2 ;'H Received',CR,LF,'Did not get Correct SOH'
BSR PRINT_STRING
BRA RECV_SECT_ERR

GOT_SOH: ;We got correct SOH so now get data
MOVE.L #SERIAL_RETRYS,D2 ;Number of times to try reading serial port before
aborting.
BSR RECV
CMP.B #$FF,D2 ;Return with FF in D2 if all is OK
BNE RECV_HDR_TIMEOUT

MOVE.B D1,D5 ;D5=BLOCK #
MOVE.L #SERIAL_RETRYS,D2 ;Number of times to try reading serial port before
aborting.
BSR RECV
CMP.B #$FF,D2 ;GET CMA'D SECT #
BNE RECV_HDR_TIMEOUT

```

```

NOT.B   D1

CMP.B   D1,D5   ;GOOD SECTOR #?
BEQ RECV_SECTOR
        ;GOT BAD SECTOR #
LEA MODEM_ERR2,A2   ;'++BAD SECTOR # IN HDR'
BSR PRINT_STRING
BRA RECV_SECT_ERR

RECV_SECTOR:      ;Now get 128 Bytes
MOVE.B   D5,(RECV_SECT_NO) ;GET SECTOR #
CLR.B   D4   ;INIT CKSUM = 0
MOVE.B   #$80,D3 ;128 Byte sectors always

RECV_CHAR:
MOVE.L   #20*SERIAL_RETRY,S,D2   ;Number of times to try reading serial port before
aborting.
BSR RECV   ;GET CHAR
CMP.B   #$FF,D2 ;GET CMA'D SECT #
BNE RECV_HDR_TIMEOUT
MOVE.B   D1,(A3)+   ;<<< STORE CHAR >>>
ADD.B   D1,D4   ;Add in checksum
SUB.B   #1,D3   ;128 Bytes done yet?
BNE RECV_CHAR

        ;NEXT VERIFY CHECKSUM
MOVE.L   #SERIAL_RETRY,S,D2   ;Number of times to try reading serial port before
aborting.
BSR RECV   ;GET CHECKSUM
CMP.B   #$FF,D2 ;Return with FF in D2 if all is OK
BNE RECV_HDR_TIMEOUT

MODL_5:
CMP.B   D1,D4   ;CHECK IF CHECKSUM IS CORRECT
BNE RECV_CKSUM_ERR
MOVE.B   (RECV_SECT_NO),D2   ;GOT A SECTOR, WRITE IF = 1+PREV SECTOR
ADD.B   #1,D5   ;CALC NEXT SECTOR #
CMP.B   D5,D2   ;MATCH?
BNE DO_ACK

MOVE.B   D5,(SECTNO) ;UPDATE SECTOR #
DO_ACK:  MOVE.B   #ACK,D1
BSR SERIAL_OUT
BRA RECV_LOOP

RECV_CKSUM_ERR:
LEA MODEM_ERR3,A2
BSR PRINT_STRING
BRA RECV_SECT_ERR

GOT_EOT:      ;DONE - CLOSE UP SHOP
MOVE.B   #ACK,d1 ;ACK THE EOT
BSR SERIAL_OUT
BSR CRLF
LEA FINISH_MSG,A2   ;Speak downloading finished
BSR SPEAK_STRING
LEA TRANS_DONE,A2
EXIT2:  BSR PRINT_STRING
MODEM_DONE:
BRA LOOP

EXIT1:  LEA ABORT_MSG,A2
JMP EXIT2

```

```

CHECK_FOR_QUIT:      ;MULTIPLE ERRORS, ASK IF TIME TO QUIT
MOVE.B  #0,(ERRCT)  ;RESET ERROR COUNT
LEA QUITM,A2
BSR PRINT_STRING
BSR GETCHAR
MOVE.L  D1,-(A7)
BSR CRLF
MOVE.L  (A7)+,D1    ;Is D1 = 'R'
CMP.B   #'R',D1
BEQ DONE_CHECK
CMP.B   #'r',D1
BEQ DONE_CHECK
CMP.B   #'Q',D1
BEQ NOT_DONE_CHECK
CMP.B   #'q',D1
BEQ NOT_DONE_CHECK
CMP.B   #ESC,D1
BEQ NOT_DONE_CHECK
JMP CHECK_FOR_QUIT

NOT_DONE_CHECK:
OR.B    D1,D1      ;TURN OFF ZERO FLAG

DONE_CHECK: RTS

;===== SUPPORT ROUTINES
=====

GETLONG_D7: CLR.L   D7 ;Get a long number and place in D7 (1-8 bytes)
CLR.B    D3 ;Byte count
GETLONG1:  BSR GETNIBBLE ;Get a Hex byte in D1
CMP.B    #ESC,D2
BEQ ABORT_LONG
CMP.B    #CR,D2 ;Loop until GETNIBBLE returns $FF = CR or ','
BEQ DONE_LONG
CMP.B    #',',D2 ;Loop until GETNIBBLE returns $FF = CR or ','
BEQ DONE_LONG
CMP.B    #BLANK,D2 ;Loop until GETNIBBLE returns $FF = CR or ','
BEQ DONE_LONG
LSL.L    #4,D7
OR.B     D1,D7
ADDQ.B   #1,D3
BRA GETLONG1

ABORT_LONG: MOVE.L  #0,D7 ;Return 0, (D1 contains ESC)
MOVE.L   D1,-(A7)
MOVE.B   #CR,D1 ;Send out a CR/LF before returning
BSR PUTCHAR
MOVE.B   #LF,D1
BSR PUTCHAR
MOVE.L   (A7)+,D1

DONE_LONG: RTS ;Normal return with FFh in D1 if CR or ',' was entered. D1 = FEh if a space
was entered

GETBYTE_D7: CLR.L   D7 ;Get a Byte number and place in D7 (1-2 bytes)
BSR GETLONG_D7
AND.L    #$ff,D7 ;Return with just a Byte (D2 will normally be 2)
RTS

```

```

GETNIBBLE: CLR.B   D2   ;clear D2 flag byte
           CLR.B   D1   ;just in case
           BSR GETCHAR ;Get a HEX character (0,1,2,3...A,B,C,D,E,F in D1)
           CMP.B   #ESC,D1 ;Was an abort requested
           BEQ NIBBLE1

           CMP.B   #CR,D1 ;CR terminates data entry
           BEQ NIBBLE1
           CMP.B   #',',D1 ;',' also terminates data entry
           BEQ NIBBLE1
           CMP.B   #BLANK,D1 ;A BLANK also terminates data entry
           BEQ NIBBLE1

BSR TOUPPER ;(D1)Lower case to Upper case

SUB.B   #$30,D1 ;SEE IF LESS THAN ZERO
BLT.S   NIBBLE2

CMP.B   #$09,D1 ;SEE IF GT 9
BLE.S   NIBBLE1
SUBQ.B  #7,D1 ;NORMALIZE $A TO 10
CMP.B   #$10,D1 ;SEE IF TOO LARGE
BCC.S   NIBBLE2
RTS ;Return with nibble in D1 (0,1,2,3...F)

NIBBLE1: MOVE.B  D1,D2 ;Store ESC/CR/,/BLANK in D2
RTS

NIBBLE2: MOVE.B  #BELL,D1 ;Not a valid HEX character
BSR PUTCHAR
MOVE.B  #'?',D1
BSR PUTCHAR
MOVE.B  #ESC,D2
RTS

PUTLONG_D7: MOVE.L  D7,D6 ;Print long in D7 on CRT, Note D6 destroyed
SWAP    D6 ;Swap down upper word
BSR PUTWORD_D6
MOVE.L  D7,D6
BSR PUTWORD_D6
RTS

PUTWORD_D6: MOVE.W  D6,D1 ;Note D1 is destroyed
LSR.W   #8,D1 ;Shift upper byte to lower 8 bits
LSR.W   #4,D1 ;Shift upper byte to lower 4 bits
AND.B   #$0F,D1 ;SAVE LOWER NIBBLE
OR.B    #$30,D1 ;CONVERT TO ASCII
CMP.B   #$39,D1 ;SEE IF IT IS > 9
BLE.S   HEXOK2
ADDQ.B  #7,D1 ;ADD TO MAKE 10=>A

HEXOK2: BSR PUTCHAR
;Address lower high byte nibble
MOVE.W  D6,D1 ;Original number again to D1
LSR.W   #8,D1 ;Shift upper byte to lower 8 bits
AND.B   #$0F,D1 ;SAVE LOWER NIBBLE
OR.B    #$30,D1 ;CONVERT TO ASCII
CMP.B   #$39,D1 ;SEE IF IT IS>9

```

```

BLE.S    HEXOK3
ADDQ.B   #7,D1                ;ADD TO MAKE 10=>A
HEXOK3:  BSR  PUTCHAR

PUTBYTE_D6:                ;Print HEX value in D6
MOVE.W   D6,D1              ;Original number again to D1
LSR.W   #4,D1              ;Shift upper byte to lower 4 bits
AND.B   #$0F,D1            ;SAVE LOWER NIBBLE
OR.B    #$30,D1            ;CONVERT TO ASCII
CMP.B   #$39,D1            ;SEE IF IT IS>9
BLE.S   HEXOK4
ADDQ.B   #7,D1                ;ADD TO MAKE 10=>A
HEXOK4:  BSR  PUTCHAR
                ;Address lower high byte nibble
MOVE.W   D6,D1              ;Original number again to D1
AND.B   #$0F,D1            ;SAVE LOWER NIBBLE
OR.B    #$30,D1            ;CONVERT TO ASCII
CMP.B   #$39,D1            ;SEE IF IT IS>9
BLE.S   HEXOK5
ADDQ.B   #7,D1                ;ADD TO MAKE 10=>A
HEXOK5:  BSR  PUTCHAR
RTS      ;All done

PUTBITS_D6:                ;Display Byte bit pattern in D6
MOVE.L   D3,-(A7)          ;Save D3
MOVE.L   D2,-(A7)          ;Save D2
MOVE.B   #7,D3             ;Bit indicator (7,6,5...0)
MOVE.B   #8,D2             ;Bit count

PUTBIT1:  BTST    D3,D6
BEQ SHOW_0
MOVE.B   #'1',D1
BSR  PUTCHAR
BRA NEXT_BIT

SHOW_0:  MOVE.B   #'0',D1
BSR  PUTCHAR

NEXT_BIT: SUBQ.B   #1,D3
SUBQ.B   #1,D2             ;8 bits total
BNE PUTBIT1
MOVE.L   (A7)+,D2         ;Restore D2
MOVE.L   (A7)+,D3         ;Restore D3
RTS

;----- MAIN ROUTINE TO PRINT A CHARACTER ON CONSOLE -----
;-----

                ;Send ASCII character in D1
PUTCHAR:
IFNE SIMMULATOR                ;If SIMMULATOR = 1, then send character via software int
MOVE     #6,D0                ;Send a character (in D1), to CRT
TRAP    #15
RTS
ENDC

IFEQ SIMMULATOR                ;If SIMMULATOR = 0, then send via console I/O port (or serial port)
MOVE.L   D5,-(A7)            ;> Save D5
MOVE.L   A0,-(A7)            ;> Save A0
MOVE.L   #IOBYTE,A0         ;Point to IOBYTE Port on SMB
MOVE.B   (A0),D5             ;Check if data is to be sent to the serial port
AND.B   #$20,D5

```

```

TST.B   D5
BNE PUTCHAR0    ;Jump to simple Propeller port
BSR SERIAL_OUT ;Call serial output routine
MOVE.L  (A7)+,A0    ;Restore A0
MOVE.L  (A7)+,D5    ;Restore D5
RTS      ;Return from subroutine, char in D1

PUTCHAR0: MOVE.L  (A7)+,A0    ;< Restore A0
PUTCHAR1: MOVE.B  (A0),D5 ;Check CRT status is ready to recieve character
AND.B   #$04,D5
TST.B   D5
BEQ PUTCHAR1
MOVE.B  D1,(A1) ;Output ASCII (in D1) to hardware port 01H
MOVE.L  (A7)+,D5    ;< Restore D5
RTS      ;Return from subroutine

ENDC

;----- MAIN ROUTINE TO GET A CHARACTER FROM CONSOLE -----
;-----

;A0 has console status port, A1 has console data port

GETCHAR:
IFNE SIMMULATOR    ;If SIMMULATOR = 1, then echo character via software int
MOVE.B  #5,D0    ;Get a character from keyboard, put in D1 (NOTE will be echoed)
TRAP   #15
RTS

ENDC

IFEQ SIMMULATOR    ;If SIMMULATOR = 0, then echod character via PUTCHAR
MOVE.L  D5,-(A7)    ;> Save D5
MOVE.L  A0,-(A7)    ;> Save A0
MOVE.L  #IOBYTE,A0 ;Point to IOBYTE Port on SMB
MOVE.B  (A0),D5 ;Check if data is to be sent to the serial port
AND.B   #$20,D5
TST.B   D5
BRA GETCHAR0    ;Jump to simple Propeller port
;
BNE GETCHAR0
BSR SERIAL_IN  ;Call serial input routine (currently not working!)
MOVE.L  (A7)+,A0    ;Restore A0
MOVE.L  (A7)+,D5    ;Restore D5
RTS      ;Return from subroutine, char in D1

GETCHAR0: MOVE.L  (A7)+,A0    ;< Restore A0 (console status port)
GETCHAR1: MOVE.B  (A0),D5 ;Get a keyboard character in D1
AND.B   #$02,D5
TST.B   D5 ;Are we ready
BEQ GETCHAR1
MOVE.B  (A1),D1 ;Get ASCII (in D1) from hardware port 01H
BSR PUTCHAR ;Echo it on console
MOVE.L  (A7)+,D5    ;< Restore D5
RTS      ;Return from subroutine, char in D1

ENDC

GETSTAT: MOVE.B  (A0),D1 ;Get a keyboard status in D1, Z= nothing, 2 = char present
AND.B   #$02,D1
TST.B   D1
RTS

```

```

;----- SERIAL PORT OUTPUT CHARACTER ROUTINE -----
-----
SERIAL_OUT: MOVE.L  D5,-(A7)    ;> Save D5
             MOVE.L  D2,-(A7)    ;> Save D2
             MOVE.L  A0,-(A7)    ;> Save A0
             MOVE.L  #ACTL,A0    ;Point to Control port of Zilog serial chip
             MOVE.W  #512,D2    ;Will check status 512 times (only)

SERIAL_OUT_STAT:
             MOVE.B  (A0),D5    ;Check serial port is ready
             AND.B   #$04,D5
             TST.B   D5
             BNE SEND_SERIAL    ;Ready to send
             SUB.W   #1,D2      ;Decraae loop count
             TST.W   D2
             BNE SERIAL_OUT_STAT
             MOVE.B  #0,D1      ;Return empty just in case

SERIAL_DONE:
             MOVE.L  (A7)+,A0    ;< Restore A0
             MOVE.L  (A7)+,D2    ;< Restore D2
             MOVE.L  (A7)+,D5    ;< Restore D5
             RTS        ;Return from subroutine, char in D1

SEND_SERIAL:
             MOVE.L  #ADTA,A0    ;Point to data port of Zilog serial chip
             MOVE.B  D1,(A0)
             BRA SERIAL_DONE

;----- SERIAL PORT INPUT CHARACTER ROUTINE -----
-----
;For XMODEM input
RECV:      MOVE.L  A3,-(A7)    ;> Save A3
           BSR SERIAL_IN_CORE ;D2 will contain delay countdown
           MOVE.L  (A7)+,A3    ;< Restore A3
           RTS

;For other serial input
SERIAL_IN: MOVE.L  A3,-(A7)    ;> Save A3
           MOVE.L  #SERIAL_RETRY,D2 ;Default number of times to try port before aborting
           BSR SERIAL_IN_CORE
           MOVE.L  (A7)+,A3    ;< Restore A3
           RTS

SERIAL_IN_CORE:
           MOVE.L  #ACTL,A3    ;Point to Control port of Zilog serial chip
           MOVE.W  #$5,D1
           MOVE.B  D1,(A3)    ;Lower RTS line
           MOVE.W  #$EA,D1
           MOVE.B  D1,(A3)
           nop
           nop
           nop
           nop
SERIAL_IN2: MOVE.B  (A3),D1
           AND.B   #$01,D1
           CMP.B   #$01,D1
           BEQ SERIAL_IN3    ;Get serial data
           SUB.L   #1,D2
           TST.W   D2
           BNE SERIAL_IN2
           MOVE.B  #0,D2      ;Return with 0 in D2 if timeout
           MOVE.B  #0,D1      ;Return with 0 in D1 if timeout

```



```

RTS

SERIAL_IN3: MOVE.L #ADTA,A3      ;Point to data port of Zilog serial chip
            MOVE.B (A3),D1      ;Get byte of data, put in D1
            MOVE.B #$FF,D2      ;Return with FF in D2 if all is OK
            RTS

```

```

;----- MAIN ROUTINE TO PRINT A STRING ON CONSOLE -----
---
```

```

PRINT_STRING:      ;Print string up to terminating \0
                MOVE.B (A2)+,D1
                TST.B D1
                BEQ PRINT_DONE
                BSR PUTCHAR
                BRA PRINT_STRING
PRINT_DONE: RTS

```

```

CRLF:            MOVE.B #CR,D1  ;Send CR/LF to CRT
                BSR PUTCHAR
                MOVE.B #LF,D1
                BSR PUTCHAR
                RTS

```

```

PUT_TAB:         MOVE.B #TAB,D1 ;Send TAB to CRT
                BSR PUTCHAR
                RTS

```

```

SPACE:          MOVE.B #BLANK,D1 ;SPACE to CRT
                BSR PUTCHAR
                RTS

```

```

TOUPPER:        CMP.B #$40,D1  ;LC->UC in D1
                BCS UPPER_DONE
                CMP.B #$7B,D1
                BCC UPPER_DONE
                AND.B #$5F,D1
UPPER_DONE: RTS

```

```

UPPER_DONE: RTS

```

```

ERROR:          LEA ErrorMsg,A2 ;Show unknown error
                BSR PRINT_STRING
                BRA LOOP

```

```

NOT_DONE:       LEA NotDoneMsg,A2 ;Code not done yet
                BSR PRINT_STRING
                BRA LOOP

```

```

                ;Send character in D1 to Console IO board speaker
SPEAKOUT:       MOVE.L A3,-(A7)  ;> Save A3
                MOVE.L D2,-(A7)  ;> Save D2
                MOVE.L D3,-(A7)  ;> Save D3
                MOVE.L #255,D2 ;Will try 255 times, then timeout
                MOVE.L #BCTL,A3

```

```

SOUT1:          MOVE.L (A3),D3
                AND.B #$04,D3
                BNE SENDS
                SUB.B #1,D2
                BNE SOUT1

```

```

SOUT2:          MOVE.L (A7)+,D3  ;< Restore D3

```

```

MOVE.L (A7)+,D2    ;< Restore D2
MOVE.L (A7)+,A3    ;< Restore A3
RTS

```

```

SENDS:    MOVE.L #BDTA,A3
           MOVE.B D1,(A3) ;Send actual character to data port
;         BSR PUTCHAR ;<---- For debugging, display character ---
           MOVE.L #SPEAKER_DELAY,D3 ;For some reason we need this delay
SENDS1:   SUB.L #1,D3 ;If not characters get dropped!
           TST.L D3
           BNE SENDS1
           MOVE.B #5,D3 ;Sel register 5
           MOVE.L #BCTL,A3 ;Raise RTS line to prevent the next character arriving
           MOVE.B D3,(A3)
           MOVE.B #$E8,D3
           MOVE.B D3,(A3)
           BRA SOUT2

```

;ROUTINE TO SEND A STRING IN (A2) TO TALKER, terminate with 0 (or CR)

```

SPEAK_STRING:
MOVE.B (A2)+,D1
CMP.B #0,D1
TST.B D1
BEQ SPEAK_DONE
CMP.B #CR,D1
BEQ SPEAK_DONE
BSR SPEAKOUT
BRA SPEAK_STRING
SPEAK_DONE: MOVE.B #CR,D1 ;Flush speaker que
             BRA SPEAKOUT
             RTS

```

```

TEST_SERIAL:
LEA SERIAL_TEST_MSG,A2 ;Will show mesage explaining the test
BSR PRINT_STRING
TEST_SERIAL1:
BSR SERIAL_IN
CMP.B #ESC,D1 ;If ESC return to main loop
BEQ TEST_SERIAL_DONE
BSR SERIAL_OUT
BRA TEST_SERIAL1
TEST_SERIAL_DONE:
LEA SERIAL_TEST_DONE_MSG,A2 ;Will show mesage explaining the test
BSR PRINT_STRING
BRA loop ;Back to start for next command

```

```

SERIAL_INITILIZE_A:
MOVE.L #ACTL,A2 ;ZILOG SCC base A port
MOVE.L #14,D2 ;Byte count (14), for below
LEA SCCINIT_A,A3 ;Start of SCCINIT table
SCC_1:  MOVE.B (A3)+,D5 ;Table of Zilog SCC initialization values
        MOVE.B D5,(A2) ;Program the SCC Channel B (A1,A3 or 10,12H) for 19K Baud
        SUB.B #1,D2 ;All 14 values
        TST.B D2
        BNE SCC_1
        RTS

```

```

SERIAL_INITILIZE_B:
MOVE.L #BCTL,A2 ;ZILOG SCC base B port

```

```

MOVE.L #14,D2 ;Byte count (14), for below
LEA SCCINIT_B,A3 ;Start of SCCINIT table
SCC_2: MOVE.B (A3)+,D5 ;Table of Zilog SCC Initialization values
MOVE.B D5,(A2) ;Program the SCC Channel B (A1,A3 or 10,12H) for 19K Baud
SUB.B #1,D2 ;All 14 values
TST.B D2
BNE SCC_2
RTS

```

```

;-----
-----

ctable      dc.l    MEM_MAP ;A      ;Display Memory Map
           dc.l    ERR ;B
           dc.l    XMODEM_BIN ;C      ;Upload an XModem .bin file
           dc.l    DISPLAY_RAM ;D      ;Display Memory contents (Read RAM in Bytes)
           dc.l    ECHO_ASCII ;E      ;Echo ASCII keyboard character to Console
           dc.l    FILL_RAM ;F      ;Fill memory contents
           dc.l    GOTO_RAM ;G      ;Jump to a ADDRESS location
           dc.l    HEX_MATH ;H      ;Add & Subtract two Hex numbers
           dc.l    ERR ;I      ;Put CMOS-RTC Time & Date on CRT
           dc.l    ERR ;J
           dc.l    SHOW_MENU ;K      ;Display this menu
           dc.l    TEST_INTS ;L      ;Test Interrupt hardware
           dc.l    MOVE_RAM ;M      ;Move memory
           dc.l    MY_IDE ;N      ;Sub-menu to test/diagnose IDE Board
           dc.l    ERR ;O
           dc.l    ERR ;P
           dc.l    QUERY_PORT ;Q      ;Query In or Out to a port
           dc.l    ERR ;R
           dc.l    SUBS_RAM ;S      ;Substitute byte values in RAM
           dc.l    ASCII_RAM ;T      ;Show ASCII values in RAM
           dc.l    TEST_SERIAL ;U      ;Test serial port
           dc.l    VERIFY_RAM ;V      ;Verify two memory regions are the same
           dc.l    ERR ;W
           dc.l    SIGNALS ;X      ;Setup for hardware S-100 bus signals test
           dc.l    PATCH ;Y      ;Quick patch to move RAM 4000H-9000H to F4000H & JUMP

to it      dc.l    JMP_Z80 ;Z      ;Return back to Z80 master

IDE_TABLE  dc.l    SET_DRIVE_A ; "A" Select Drive A
           dc.l    SET_DRIVE_B ; "B" Select Drive B
           dc.l    ERR ; "C" LOAD CPM68K (If present)
           dc.l    DISPLAY ; "D" Sector contents display:- ON/OFF
           dc.l    RAMCLEAR ; "E" Clear RAM buffer
           dc.l    FORMAT ; "F" Format current disk
           dc.l    ERR ; "G" Restore backup
           dc.l    ERR ; "H" Backup partition
           dc.l    NEXT_SECT ; "I" Next Sector
           dc.l    PREV_SECT ; "J" Previous sector
           dc.l    IDE_LOOP ; "K"
           dc.l    SET_LBA ; "L" Set LBA value (Set Track,sector)
           dc.l    ERR ; "M"
           dc.l    SPINDOWN ; "N" Power down hard disk command
           dc.l    DRIVE_ID ; "O" Show current Drive ID
           dc.l    ERR ; "P"
           dc.l    ERR ; "Q"
           dc.l    READ_SEC ; "R" Read sector to data buffer
           dc.l    SEQ_SEC_RD ; "S" Sequential sec read and display contents
           dc.l    ERR ; "T"
           dc.l    SPINUP ; "U" Power up hard disk command

```

```

dc.1  N_RD_SEC       ; "V"  Read N sectors
dc.1  WRITE_SEC     ; "W"  Write data buffer to current sector
dc.1  N_WR_SEC     ; "X"  Write N sectors
dc.1  COPY_AB      ; "Y"  Copy Drive A to Drive B
dc.1  VERIFY_AB    ; "Z"  Verify Drive A:= Drive B:

```

```

;BOTH CONSOLE IO BOARD's SSC's are set for 19,200 BAUD

```

```

SCCINIT_A:  dc.b  $04      ;Point to WR4
            dc.b  $44      ;X16 clock,1 Stop,NP
            dc.b  $03      ;Point to WR3
            dc.b  $C1      ;Enable reciever, Auto Enable, Recieve 8 bits
;          dc.b  $E1      ;Enable reciever, No Auto Enable, Recieve 8 bits (for CTS bit)

            dc.b  $05      ;Point to WR5
            dc.b  $EA      ;Enable, Transmit 8 bits
            dc.b  $0B      ;Set RTS,DTR, Enable. Point to WR11
            dc.b  $56      ;Recieve/transmit clock = BRG
            dc.b  $0C      ;Point to WR12
;          dc.b  $40      ;Low Byte 2400 Baud
;          dc.b  $1E      ;Low Byte 4800 Baud
;          dc.b  $0E      ;Low Byte 9600 Baud
;          dc.b  $06      ;Low byte 19,200 Baud
;          dc.b  $02      ;Low byte 38,400 Baud <<<<<<<<<<< XModem I/O
;          dc.b  $00      ;Low byte 76,800 Baud
            dc.b  $0D      ;Point to WR13
            dc.b  $00      ;High byte for Baud
            dc.b  $0E      ;Point to WR14
            dc.b  $01      ;Use 4.9152 MHz Clock. Note SD Systems uses a 2.4576 MHz clock,
enable BRG
            dc.b  $0F      ;Point to WR15
            dc.b  $00      ;Generate Int with CTS going high

SCCINIT_B:  dc.b  $04      ;Point to WR4
            dc.b  $44      ;X16 clock,1 Stop,NP
            dc.b  $03      ;Point to WR3
            dc.b  $C1      ;Enable reciever, Auto Enable, Recieve 8 bits
            dc.b  $05      ;Point to WR5
            dc.b  $EA      ;Enable, Transmit 8 bits
            dc.b  $0B      ;Set RTS,DTR, Enable. Point to WR11
            dc.b  $56      ;Recieve/transmit clock = BRG
            dc.b  $0C      ;Point to WR12
            dc.b  $06      ;Low byte 19,200 Baud <<<<<<<<<< Note Speech synthizer
defaults to this value
            dc.b  $0D      ;Point to WR13
            dc.b  $00      ;High byte for Baud
            dc.b  $0E      ;Point to WR14
            dc.b  $01      ;Use 4.9152 MHz Clock. Note SD Systems uses a 2.4576 MHz clock,
enable BRG
            dc.b  $0F      ;Point to WR15
            dc.b  $00      ;Generate Int with CTS going high

Signon      dc.b  CR,LF,'68000 Monitor V2.5 John Monahan 05/2/2014',CR,LF,0
Prompt     dc.b  CR,LF,'>',0
Menu       dc.b  CR,LF
            dc.b  'A=Memmap      C=XMODEM(Bin) D=Disp RAM      E=Echo           F=Fill RAM'
            dc.b  CR,LF
            dc.b  'G=Goto RAM    H=Math                I=Time           K=Menu           L=Test Ints'
            dc.b  CR,LF
            dc.b  'M=Move RAM    N=IDE Menu           Q=Port I/O       U=Serial Test    S=Subs RAM'
            dc.b  CR,LF

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```

dc.b 'T=Type RAM V=Verify RAM X=Signals Y=Patch Z=Back to Z80'
dc.b CR,LF,LF,0

SMMSG dc.b 'THE 68 THOUSAND ROM MONITOR, VERSION 2.5 IS NOW ACTIVE',0

BadCmdMsg dc.b CR,LF,BELL,'Bad Command. Got a vlaue of ',0
ErrorMsg dc.b CR,LF,BELL,'Invalid entry',CR,LF,0
PortMsg dc.b CR,LF,'Port ',0
PortMsg2 dc.b CR,LF,'Send to Port ',0
NotDoneMsg dc.b CR,LF,BELL,'Sorry code for this command has not been written
yet',CR,LF,0
HEX_Data dc.b CR,LF,'Sum = ',0
HEX_Data2 dc.b 'H Difference = ',0

BUS_ERROR_MSG dc.b CR,LF,'Bus Error interrupt recieved',CR,LF,0
ADDRESS_ERROR_MSG dc.b CR,LF,'Address Error interrupt recieved',CR,LF,0
ILLEGAL_ERROR_MSG dc.b CR,LF,'Illegal Opcode interrupt recieved',CR,LF,0
ZERO_ERROR_MSG dc.b CR,LF,'Zero Error interrupt recieved',CR,LF,0
PRIVILEGE_ERROR_MSG dc.b CR,LF,'Priviledge Error interrupt recieved',CR,LF,0
TRACE_ERROR_MSG dc.b CR,LF,'Trace Error interrupt recieved',CR,LF,0
SPURIOUS_INT_MSG dc.b CR,LF,'Spurious interrupt recieved',CR,LF,0
L1_INTERRUPT_MSG dc.b CR,LF,'L1 (or NMI) interrupt recieved',CR,LF,0
L2_INTERRUPT_MSG dc.b CR,LF,'L2 interrupt recieved',CR,LF,0
L3_INTERRUPT_MSG dc.b CR,LF,'L3 interrupt recieved',CR,LF,0
L4_INTERRUPT_MSG dc.b CR,LF,'L4 interrupt recieved',CR,LF,0
L5_INTERRUPT_MSG dc.b CR,LF,'L5 interrupt recieved',CR,LF,0
L6_INTERRUPT_MSG dc.b CR,LF,'L6 interrupt recieved',CR,LF,0
L7_INTERRUPT_MSG dc.b CR,LF,'L7 interrupt recieved',CR,LF,0
INT_ERR_MSG dc.b CR,LF,'Undefined interrupt recieved',CR,LF,0
TRAPS_ERR_MSG dc.b CR,LF,'Undefined TRAP interrupt recieved',CR,LF,0
INTS_DONE_MSG dc.b CR,LF,'Interrupt vectors in RAM (0-400H) initilized',CR,LF,0

SIGNALS_MSG dc.b CR,LF,'Put CPU in hardware loop to test (pDBIN or pWR*)'
dc.b CR,LF,'Enter test RAM Location: ',0
Menu_lor2_MSG dc.b CR,LF,'Enter 1=pDBIN, 2=pWR* :',0
SIG_STARTED_MSG dc.b CR,LF,'Signal test loop started.....(Hit Reset to Abort)',0
ECHO_MSG dc.b CR,LF,'Will echo each ASCII character typed on keyboard. ESC to
abort',CR,LF,0
PATCH_MSG dc.b CR,LF,'Moving Code at 4000H-9000H to F4000H, Then jump to that
location',CR,LF,0
SERIAL_TEST_MSG dc.b CR,LF,'Characters entered via serial IN port will appear on serial OUT
port.'
dc.b CR,LF,'Press ESC to abort',CR,LF,0
SERIAL_TEST_DONE_MSG dc.b CR,LF,'Serial test done. Returning to 68000 Monitor.',CR,LF,0

IDE_SIGNON0 dc.b CR,LF,LF,'IDE HDisk Test Menu Routines.',CR,LF,0
IDE_SIGNON1 dc.b 'A=Select Drive A B=Select Drive B C=Boot CPM68K D=Set Sec Display
Mode to On',CR,LF,0
IDE_SIGNON2 dc.b 'A=Select Drive A B=Select Drive B C=Boot CPM68K D=Set Sec Display
Mode to Off',CR,LF,0
IDE_SIGNON3 dc.b 'E=Clear Sec Buff F=Format Disk I=Next Sec J=Previous Sec',CR,LF
dc.b 'L=Set LBA Value N=Power Down O=Disk ID Q=LBA Display
Test',CR,LF
dc.b 'R=Read Sector S=Seq Sec Rd U=Power Up V=Read N
Sectors',CR,LF
dc.b 'W=Write Sector X=Write N Sectors X=Copy A->B Z=Verify A=B',CR,LF
dc.b '(ESC) Back to Main Menu',CR,LF
dc.b LF,'Current settings:- ',0

IDE_MENU_CMD dc.b 'Enter a Command:- ',0
IDE_HARDWARE dc.b CR,LF,'Initilizing IDE Drive hardware.',0
INIT_1_ERROR dc.b CR,LF,'Initilizing of First Drive failed. Aborting
Command.',BELL,CR,LF,LF,0

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INIT_2_ERROR      dc.b   CR,LF,'Initilizing of Second Drive failed. (Possibly not
present).',BELL,CR,LF,LF,0
BAD_DRIVE:        dc.b   CR,LF,'First Drive ID Informnation appears invalid. '
                  dc.b   '(Drive possibly not present).',CR,LF
                  dc.b   'Aborting Command.',BELL,CR,LF,LF,0

msgmdl            dc.b   CR,LF,'Drive/CF Card Information:-',CR,LF
                  dc.b   'Model: ',0
msgsn             dc.b   'S/N: ',0
msgrev           dc.b   'Rev: ',0
msgcy            dc.b   'Cylinders: ',0
msghd            dc.b   ', Heads: ',0
msgsc            dc.b   ', Sectors: ',0
msgCPMTRK        dc.b   'CPM TRK = ',0
msgCPMSEC        dc.b   ' CPM SEC = ',0
msgLBA           dc.b   ' (LBA = 00',0
MSGBracket       dc.b   ')',0
H_MSG_CRLF       dc.b   'H',CR,LF,0

NotDoneYet       dc.b   CR,LF,'Command Not Done Yet',0
CONFIRM_WR_MSG   dc.b   CR,LF,LF,BELL,'Will erase data on the current drive, '
                  dc.b   'are you sure? (Y/N)...',0
msgrd            dc.b   'Sector Read OK',CR,LF,0
msgwr            dc.b   'Sector Write OK',CR,LF,0
SET_LBA_MSG      dc.b   'Enter CPM style TRK & SEC values (in hex).',CR,LF,0
SEC_RW_ERROR     dc.b   'Drive Error, Status Register = ',0
ERR_REG_DATA     dc.b   'Drive Error, Error Register = ',0
ENTERRAM_SECL    dc.b   'Starting sector number,(xxH) = ',0
ENTERRAM_HEAD    dc.b   'Starting HEAD number,(xxH) = ',0
ENTERRAM_FTRKL   dc.b   'Enter Starting Track number,(xxH) = ',0
ENTERRAM_TRKL    dc.b   'Track number (LOW byte, xxH) = ',0
ENTERRAM_TRKH    dc.b   'Track number (HIGH byte, xxH) = ',0
ENTER_HEAD       dc.b   'Head number (01-0f) = ',0
ENTER_COUNT      dc.b   'Number of sectors to R/W (xxH) = ',0
ENTERRAM_DMA     dc.b   'Enter DMA Adress (Up to 5 digits, xxxxxH) = ',0
OVER_COUNT_10    dc.b   CR,LF,'1 & 9 sectors. Only!',CR,LF,0
OVER_COUNT_19    dc.b   CR,LF,'1 & 18 sectors. Only!',CR,LF,0
DRIVE_BUSY       dc.b   'Drive Busy (bit 7) stuck high. Status = ',0
DRIVE_NOT_READY  dc.b   'Drive Ready (bit 6) stuck low. Status = ',0
DRIVE_WR_FAULT   dc.b   'Drive write fault. Status = ',0
UNKNOWN_ERROR    dc.b   'Unknown error in status register. Status = ',0
BAD_BLOCK        dc.b   'Bad Sector ID. Error Register = ',0
UNRECOVER_ERR    dc.b   'Uncorrectable data error. Error Register = ',0
READ_ID_ERROR    dc.b   'Error setting up to read Drive ID',CR,LF,0
SEC_NOT_FOUND    dc.b   'Sector not found. Error Register = ',0
INVALID_CMD      dc.b   'Invalid Command. Error Register = ',0
TRK0_ERR         dc.b   'Track Zero not found. Error Register = ',0
UNKNOWN_ERROR1   dc.b   'Unknown Error. Error Register = ',0
CONTINUE_MSG     dc.b   CR,LF,'To Abort enter ESC. Any other key to continue. ',0
FORMAT_MSG_A     dc.b   'Fill disk sectors of Disk [A] with 0E5H',0
FORMAT_MSG_B     dc.b   'Fill disk sectors of Disk [B] with 0E5H',0
ATHOME_MSG       dc.b   CR,LF,BELL,'Already on Track 0, Sector 0',0
AT_START_MSG     dc.b   CR,LF,BELL,'Already at start of disk!',0
AT_END_MSG       dc.b   CR,LF,BELL,'At end of Disk!',0
FILL_MSG         dc.b   CR,LF,'Sector buffer area cleared to 0000....',0
READN_MSG        dc.b   CR,LF,'Read N sectors from disk.',0
WRITEN_MSG       dc.b   CR,LF,'Write N sectors to disk.',0
DiskCopyMsg      dc.b   CR,LF,'Copy CPM Partition on Drive A to Drive B (Y/N)? ',0
DiskVerifyMsg    dc.b   CR,LF,'Will verify CPM Partition on Drive A to Drive B.',0
CopyDone         dc.b   CR,LF,'Disk Copy Done.',0
VERIFY_ERR       dc.b   CR,LF,BELL,'Verify Error. ',0
VerifyDone       dc.b   CR,LF,'Disk Verify Done.',0
CR_To_Continue   dc.b   CR,LF,'Hit any key to continue.',0

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```

OK_CR_MSG      dc.b    ' OK',CR,LF,0
COPY_ERR       dc.b    CR,LF,BELL,'Sector Copy Error.',0
CURRENT_MSG_A  dc.b    '  Current Drive = [A]',CR,LF,0
CURRENT_MSG_B  dc.b    '  Current Drive = [B]',CR,LF,0
FORMAT_ERR     dc.b    CR,LF,BELL,'Sector Format Error',0
ERR_MSG        dc.b    CR,LF,BELL,'Invalid Command (or code not yet done)',CR,LF,0
DRIVE1_MSG     dc.b    '  on Drive A',CR,LF,0
DRIVE2_MSG     dc.b    '  on Drive B',CR,LF,0
IDE_SEL_A      dc.b    CR,LF,'Selecting IDE Drive A',CR,LF,0
IDE_SEL_B      dc.b    CR,LF,'Selecting IDA Drive B',CR,LF,0

MODEM_S_SIGNON dc.b    CR,LF,'Load Motorola .s File from a PC to RAM using the S100Computers IO
Board',CR,LF
              dc.b    'Zilog SCC Ports A1H & A3H. Requires RTS & CTS, 38,400 Baud.',CR,LF,0

MODEM_BIN_SIGNON dc.b    CR,LF,'Load a .bin File from a PC to RAM using the S100Computers IO
Board',CR,LF
              dc.b    'Zilog SCC Ports A1H & A3H. Requires RTS & CTS, 38,400 Baud.',CR,LF,0

RAM_DESTINATION_MSG dc.b    CR,LF,'Enter destination in RAM for data (up to 8 digits): ',0
DOWNLOAD_MSG     dc.b    'Downloading file Started.',0
RMSG             dc.b    CR,LF,'WAITING FOR SECTOR #',0
ERRSOH          dc.b    'H Received',CR,LF,'Did not get Correct SOH',CR,LF,0
MODEM_ERR2      dc.b    CR,LF,'Bad Sector # in Header',CR,LF,0
MODEM_ERR3      dc.b    CR,LF,'Bad Checksum for Sector',CR,LF,0
TOUTM           dc.b    CR,LF,'Timeout! Error count = ',0
QUITM           dc.b    CR,LF,'+++ MULTIPLE ERRORS ENCOUNTERED +++'
              dc.b    CR,LF,'Type Q To Quit, R To Retry:',0
RAM_MSG         dc.b    'H.  If OK will write to RAM location ',0
FINISH_MSG      dc.b    'Down loading of file complete.  No Errors',0
TRANS_DONE     dc.b    CR,LF,LF,'Data Transfer Is Complete',CR,LF,LF,0
BAD_HEADER      dc.b    CR,LF,'Unable to get a valid file header!',CR,LF,0
START_B_POINTER_MSG dc.b    CR,LF,'Will load .bin file data starting at RAM location ',0
START_S_POINTER_MSG dc.b    CR,LF,'Will load Motorola .s file data at RAM location ',0
ABORT_MSG       dc.b    CR,LF,LF,'Invalid Character or Program Aborted',CR,LF,0
H_MSG           dc.b    'H',0

```

```

;-----
-----
IFNE ROM_CODE      ;If ROM based Code
    ORG $00FD80F0  ;Start of Supervisor Stack area, (FD80F0H down to FD8000H)
SUPERVISOR_STACK
    DC.W    0
    ORG $00FD8100  ;Start OF RAM Area on CPU Board, (beginning at FD8100 upwards)
ENDC

IFNE S100_TEST     ;If S100 RAM based Code
    ORG $00FD80F0  ;Start of Supervisor Stack area, (FD80F0H down to FD8000H)
SUPERVISOR_STACK
    DC.W    0
    ORG $00FD8100  ;Start of RAM Area on CPU Board, (beginning at FD8100 upwards)
ENDC

IFNE SIMMULATOR   ;If SIMMULATOR
    ORG $90F0      ;Start of Supervisor Stack area (90F0 down to 9000H)
SUPERVISOR_STACK
    DC.W    0
    ORG $9100      ;Start OF RAM Area on CPU Board, (beginning at FD8100 upwards)
ENDC

```

```

BeginRAM:
IDE_BUFFER      ds.b      512      ;Buffer area for sector data
IDE_BUFFER2     ds.b      512

RAM_DMA:       dc.w      0      ;Storage or DMA address
RAM_DMA_STORE  dc.l      0
SECTOR_COUNT   dc.w      0
RAM_DRIVE_TRK  dc.w      0
RAM_DRIVE_SEC  dc.w      0

DISPLAY_FLAG   dc.b      0      ;Flag it indicate if detail sector info is to be displayed
RAM_SEC:       dc.b      0
RAM_TRK:       dc.b      0
CURRENT_IDE_DRIVE dc.b    0
CURRENT_HEAD   dc.b    0
CURRENT_TRACK_HIGH dc.b  0
CURRENT_TRACK  dc.b    0
CURRENT_SECTOR dc.b    0
SECTORS_TO_DO  dc.b    0

RECVD_SECT_NO  dc.b    0      ;For XMODEM
SECTNO         dc.b    0      ;
ERRCT         dc.b    0      ;
S_FILE_ADDRESS dc.l    0      ;Start location in RAM of S file

EndRAM:        dc.b      0      ;End of 0 cleared RAM area

    IFEQ SIMULATOR      ;If SIMULATOR = 0
        END $00FDFFFE
    ENDC

    IFNE SIMULATOR      ;If SIMULATOR = 1
        END $0000
    ENDC

```



